

# Direct measurement of optical coating thermal noise on a large frequency range

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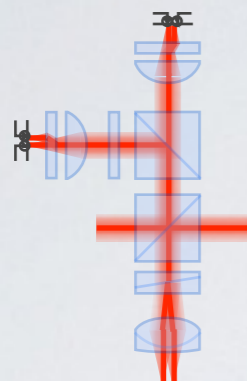
*ET Symposium – Lyon – november 19<sup>th</sup>, 2014*



**Pierdomenico Paolino**

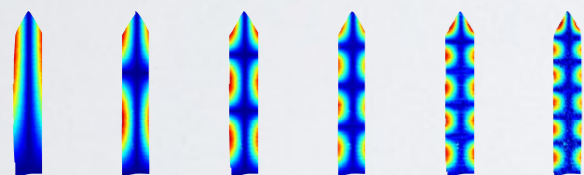
**Tianjun Li**





- Quadrature phase interferometry

- Experimental setup
  - Measurement of thermal noise



- Micro-cantilever response from thermal noise

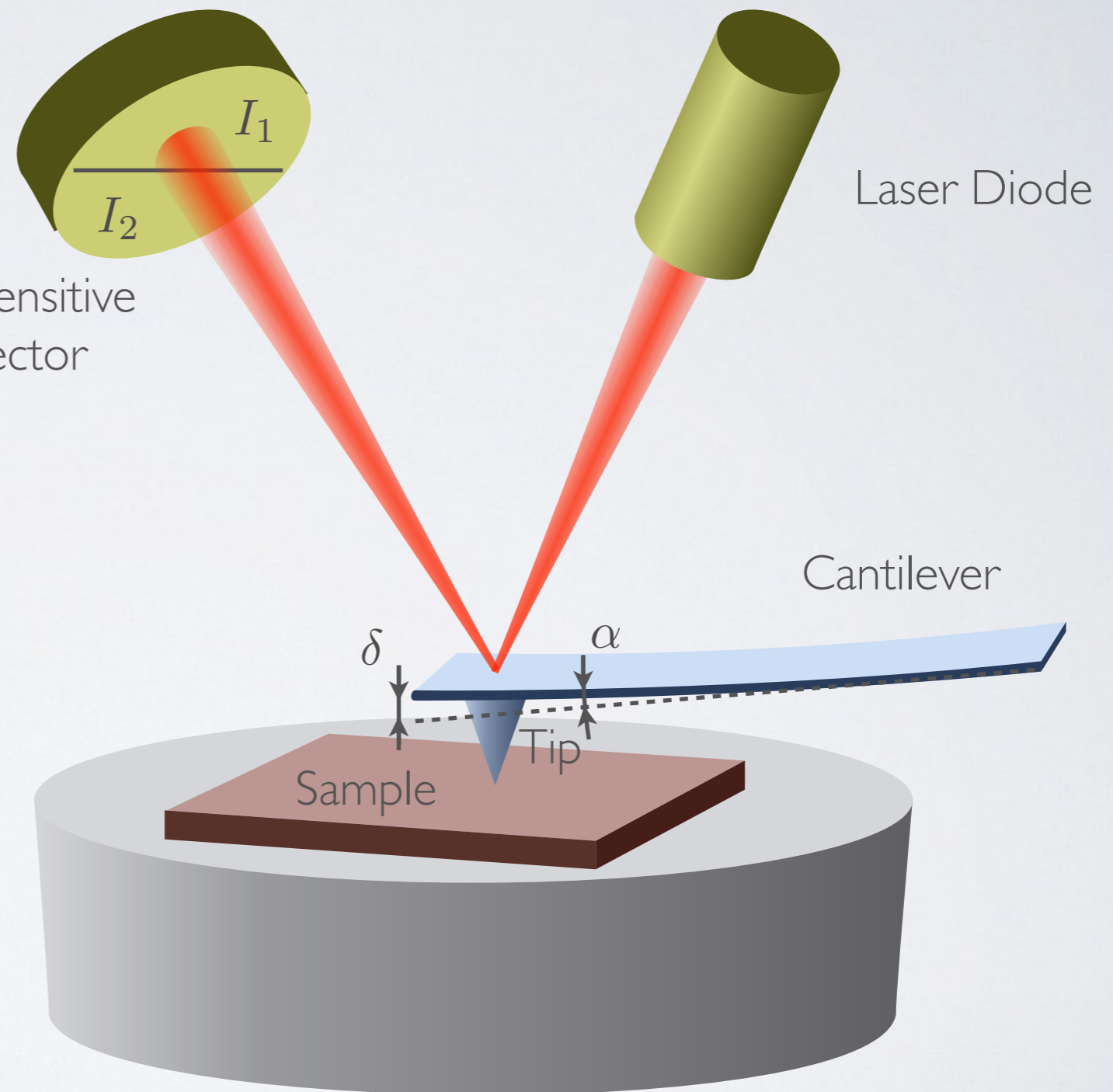
- Full measurement of response with Kramers-Kronig relations
  - Viscoelasticity of coating layer

# Commercial AFM setup

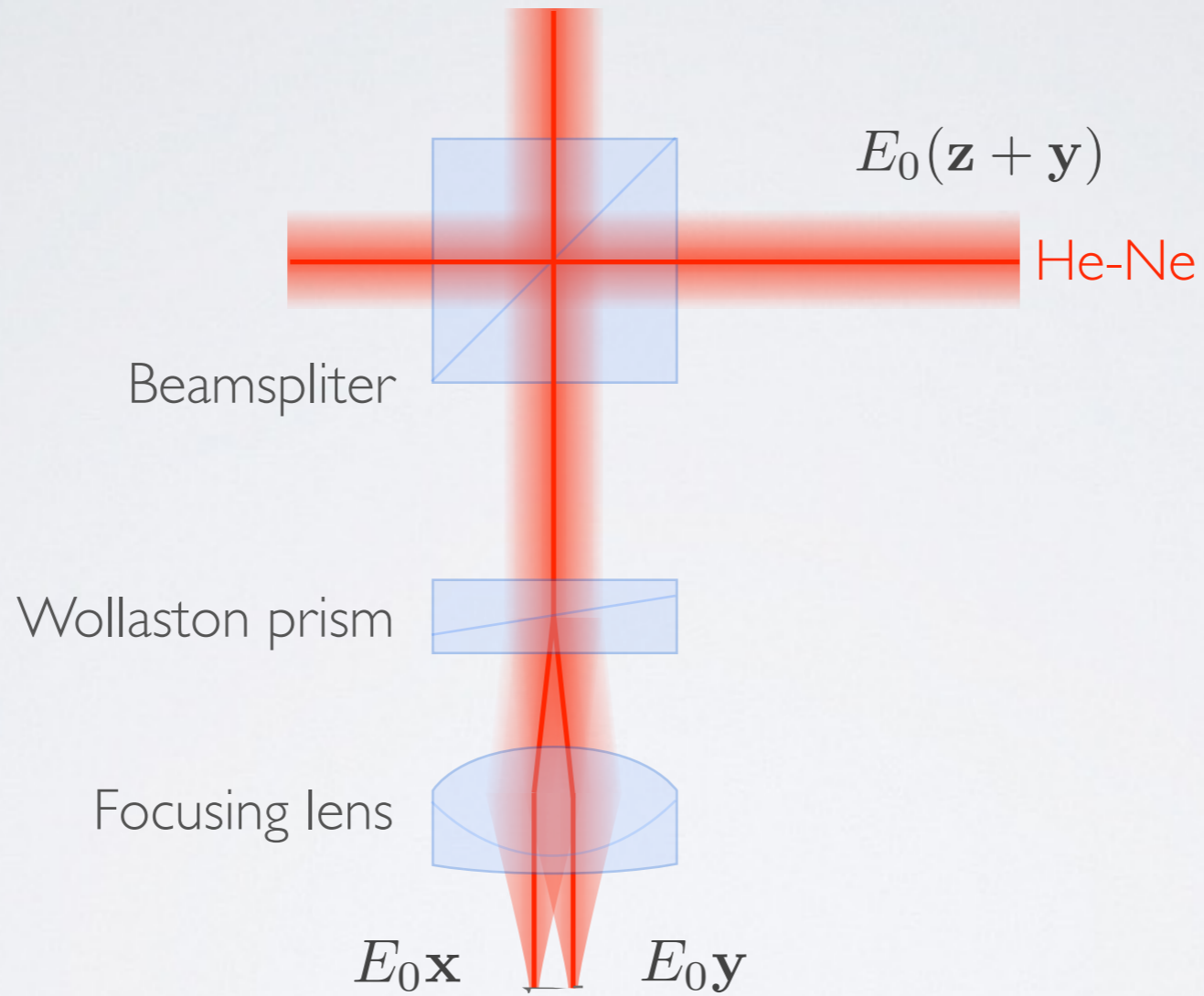
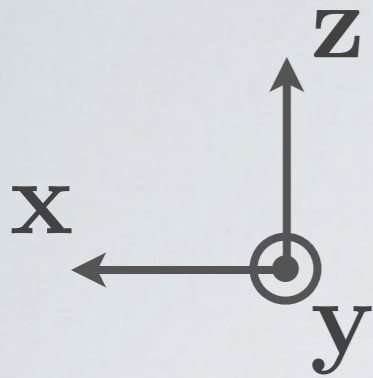
$$C_{4Q} = \frac{I_1 - I_2}{I_1 + I_2}$$

Position sensitive  
Photodetector

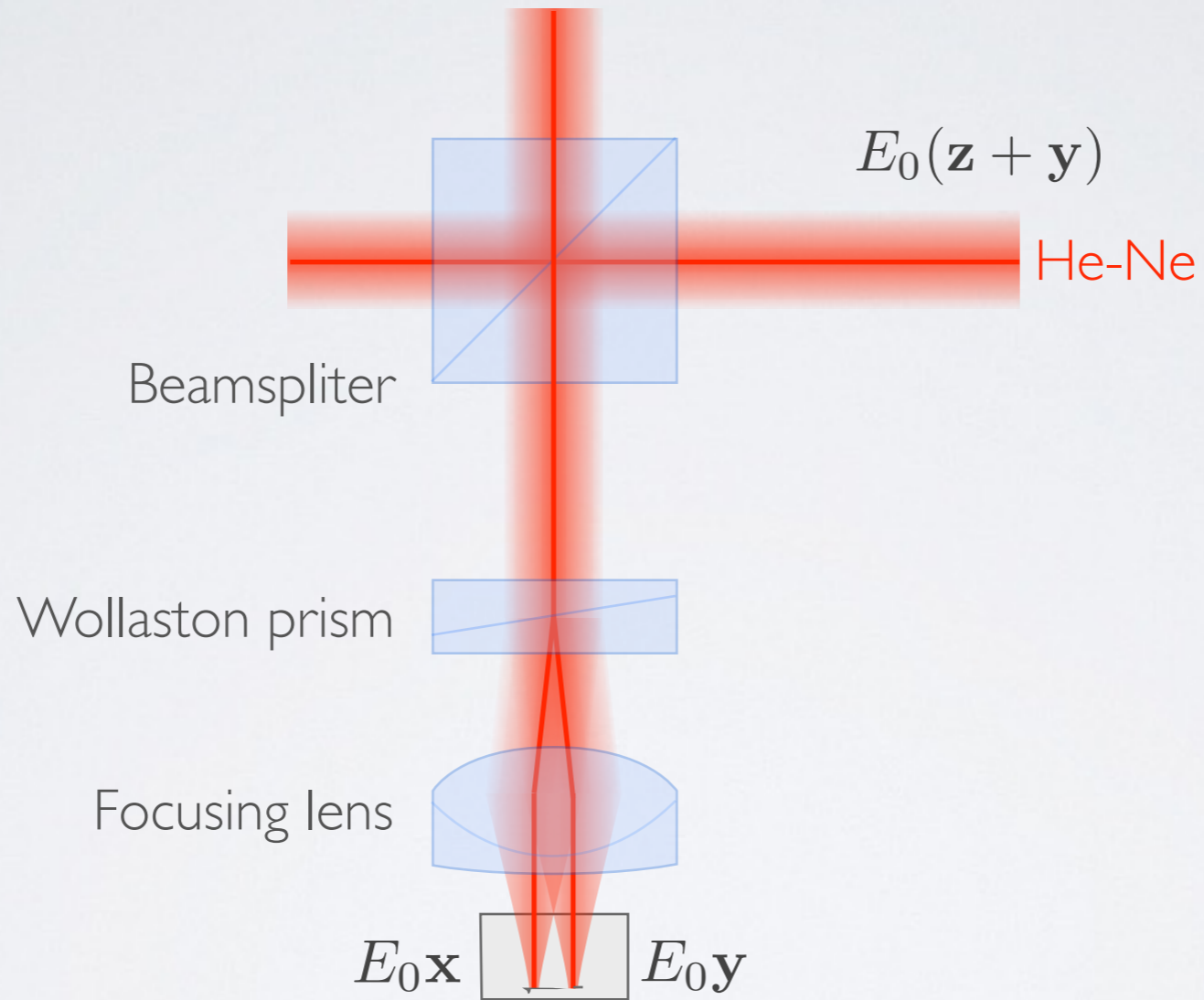
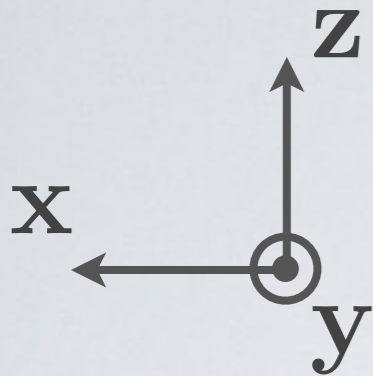
$$\delta = \left( \frac{\partial \delta}{\partial \alpha} \right) \left( \frac{\partial \alpha}{\partial C} \right) C_{4Q}$$



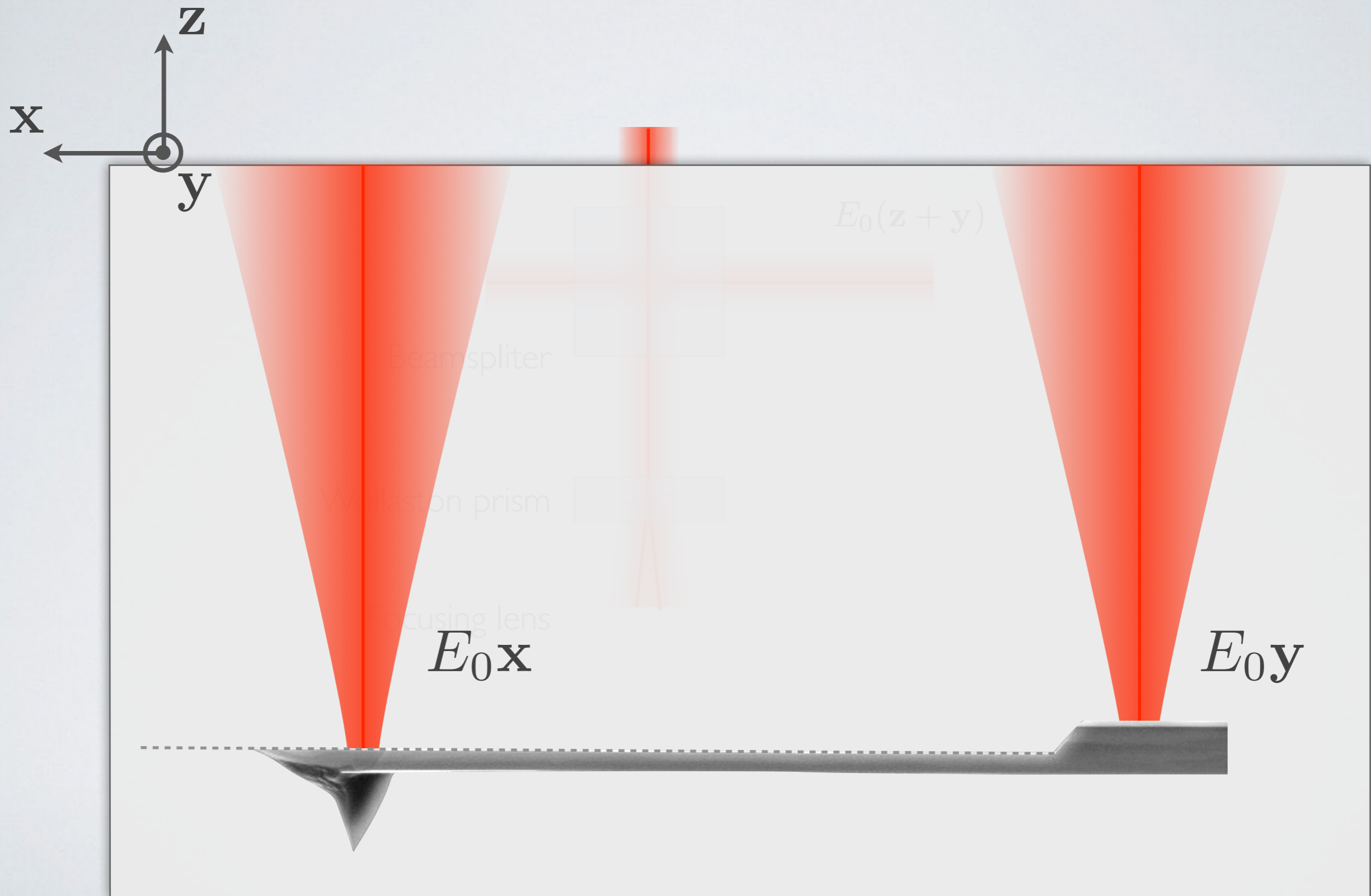
# Interferometer: measurement area



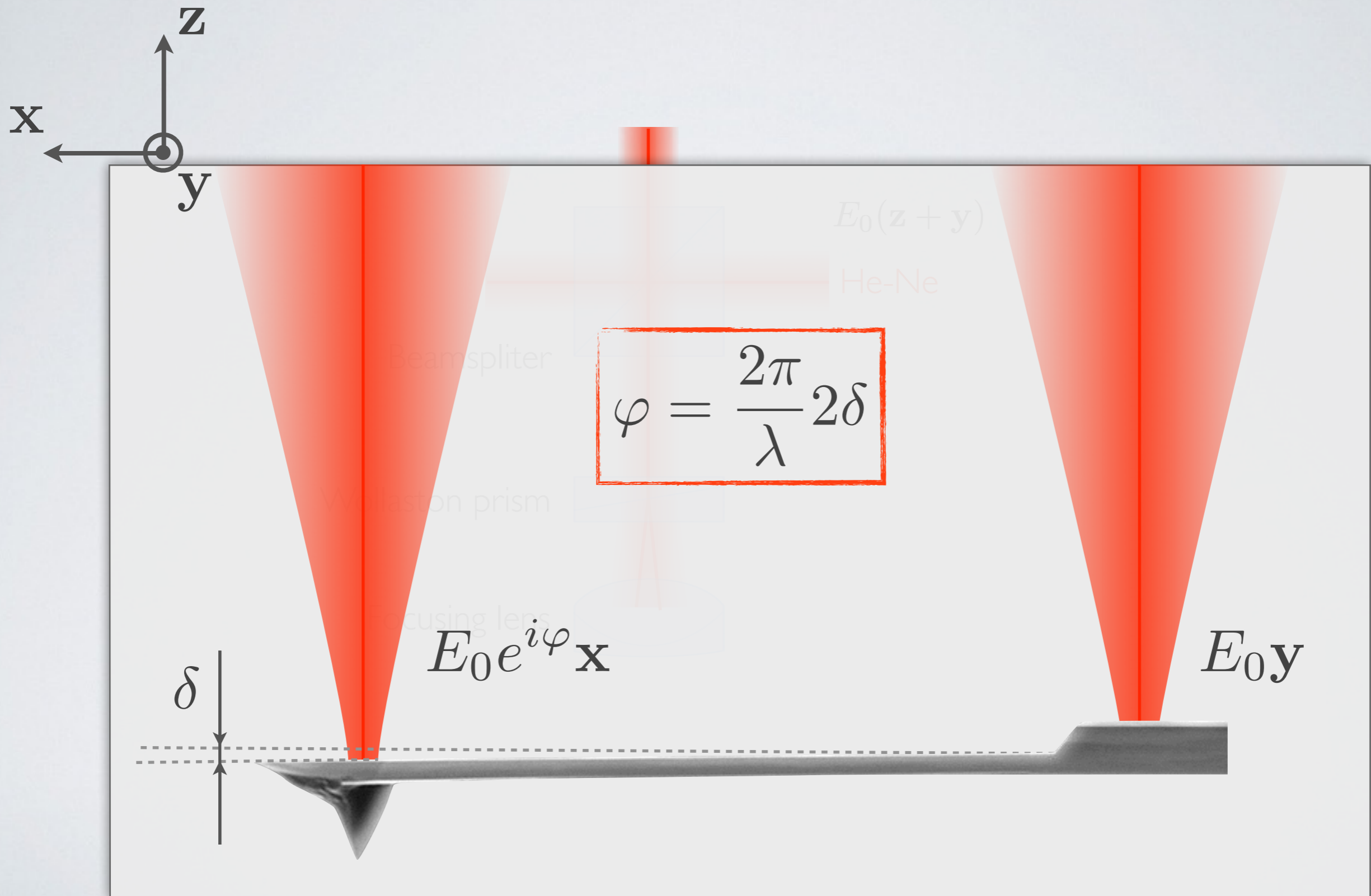
# Interferometer: measurement area



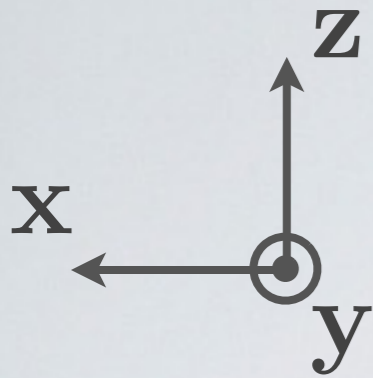
# Interferometer: measurement area



# Interferometer: measurement area

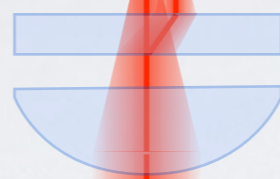


# Interferometer: analysis area

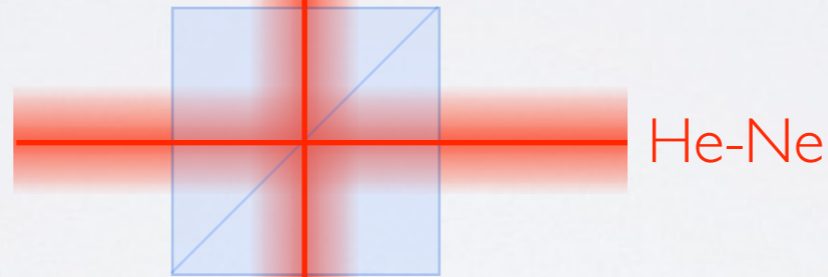


$$I_1 = E_0^2 |1 + e^{i\varphi}|^2 \quad I_2 = E_0^2 |1 - e^{i\varphi}|^2$$

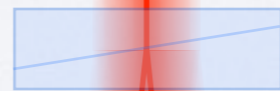
Calcite prism



$$E_0(e^{i\varphi} \mathbf{x} + \mathbf{y})$$



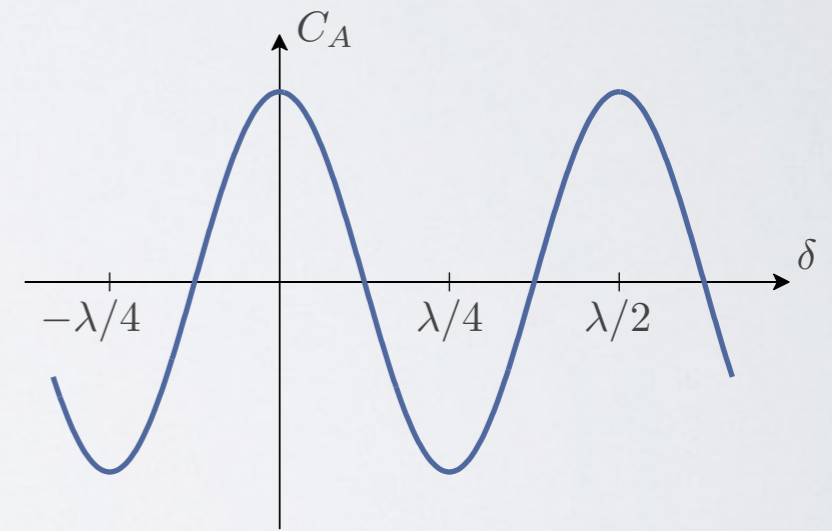
Wollaston prism



$\delta$

Photodiodes A

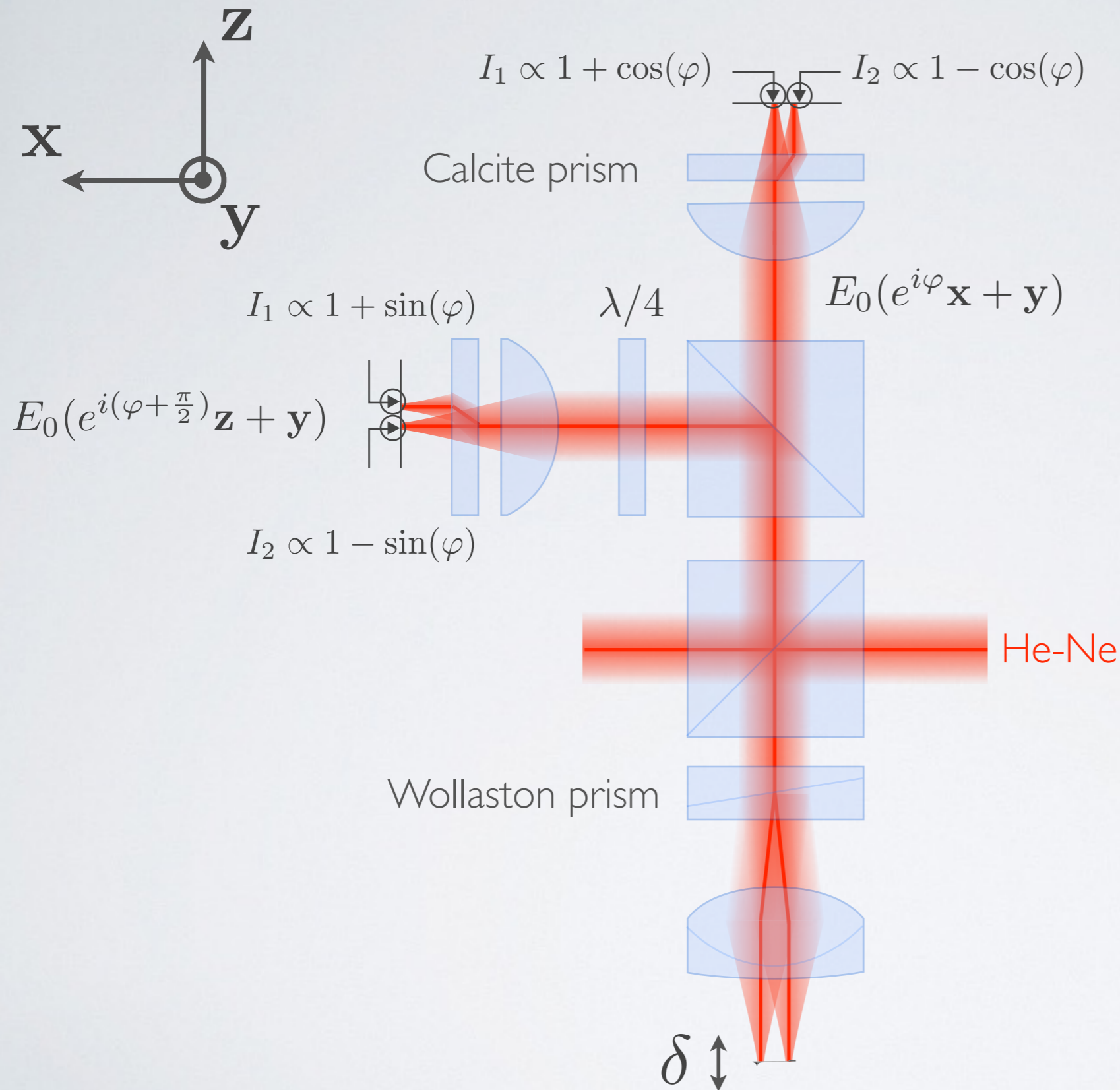
$$C_A = \frac{I_1 - I_2}{I_1 + I_2} = \cos(\varphi)$$



$$\varphi = \frac{2\pi}{\lambda} 2\delta$$



# Interferometer: analysis area

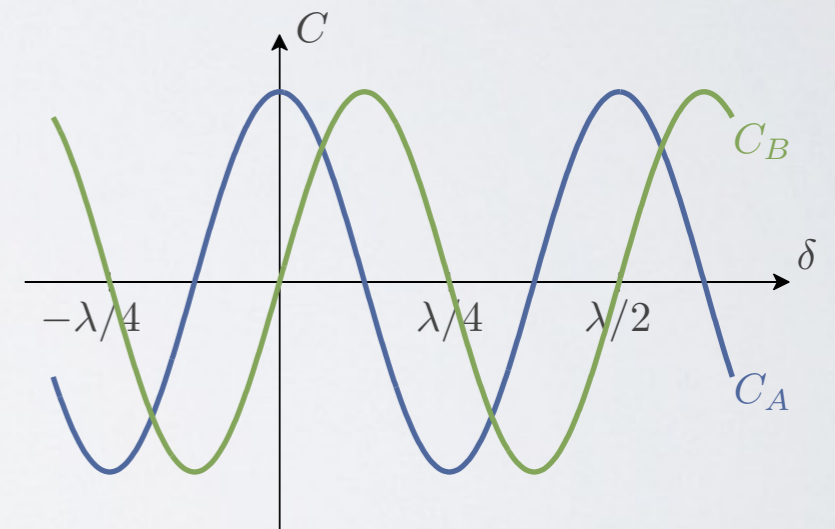


Photodiodes A

$$C_A = \cos(\varphi)$$

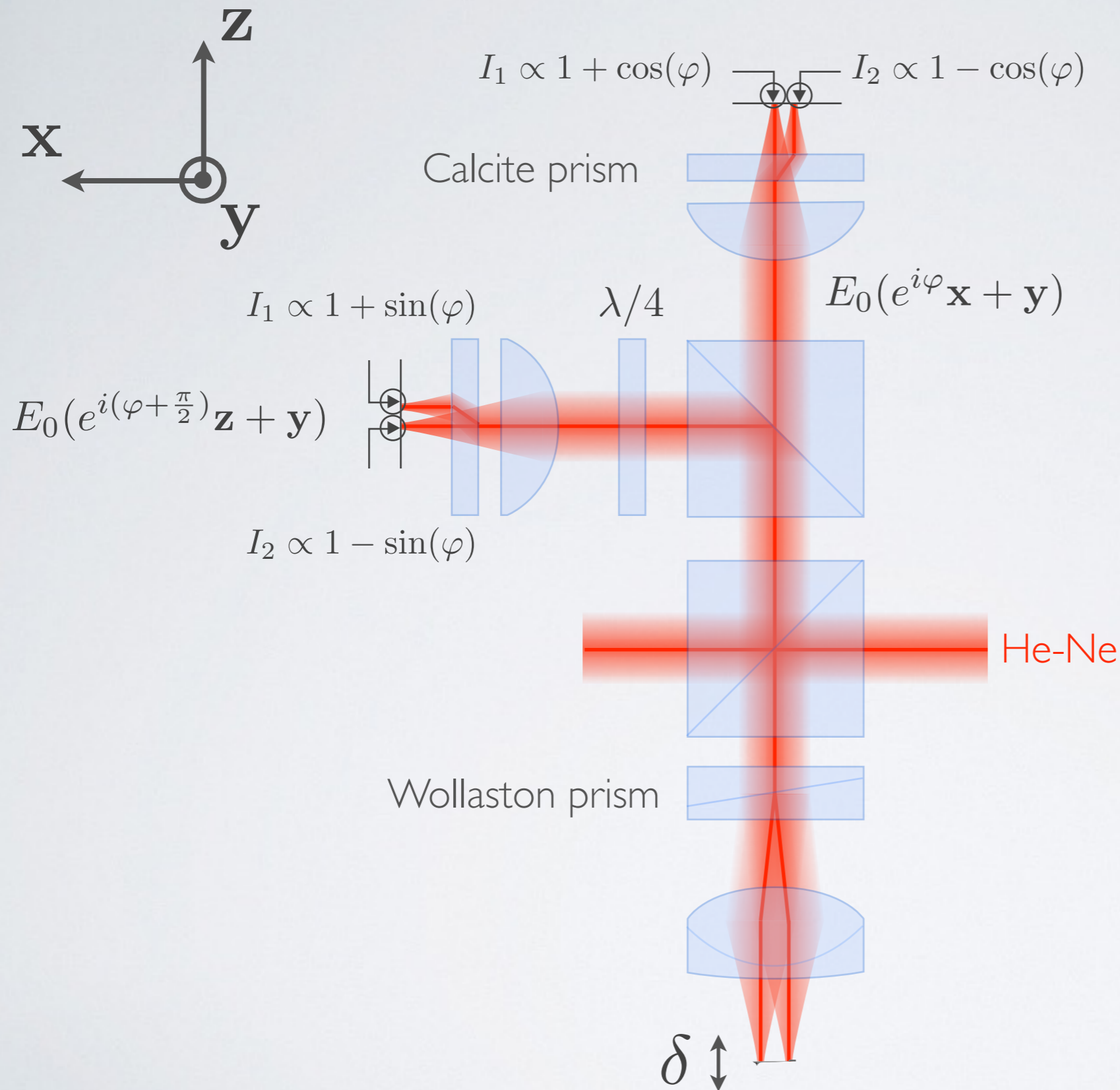
Photodiodes B

$$C_B = \sin(\varphi)$$



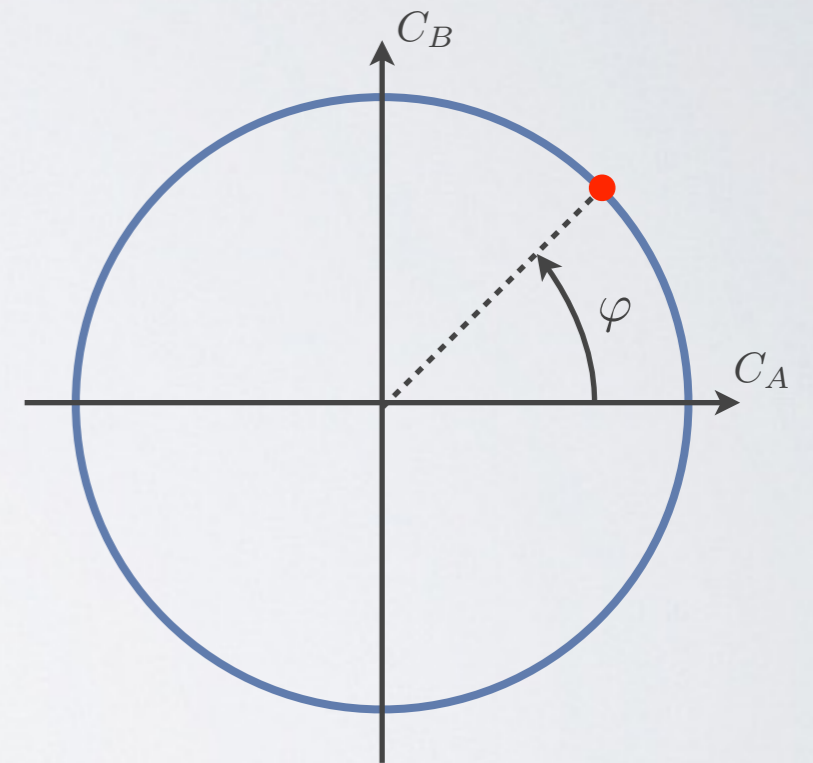
$$\varphi = \frac{2\pi}{\lambda} 2\delta$$

# Interferometer: analysis area



Photodiodes A & B

$$C^* = C_A + iC_B = e^{i\varphi}$$



$$\varphi = \frac{2\pi}{\lambda} 2\delta$$

# Interferometer: realisation

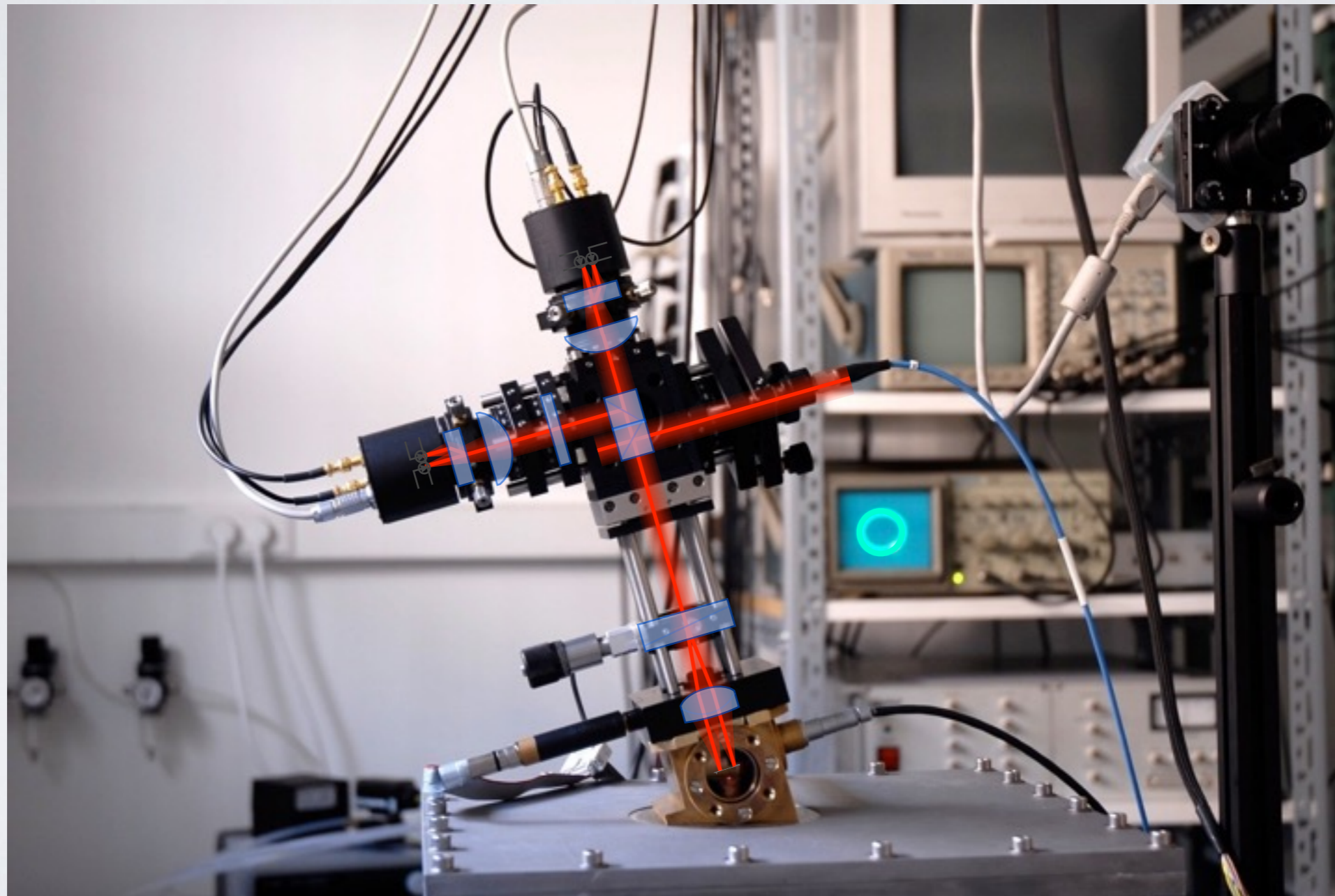
F. Vittoz  
*Atelier mécanique*

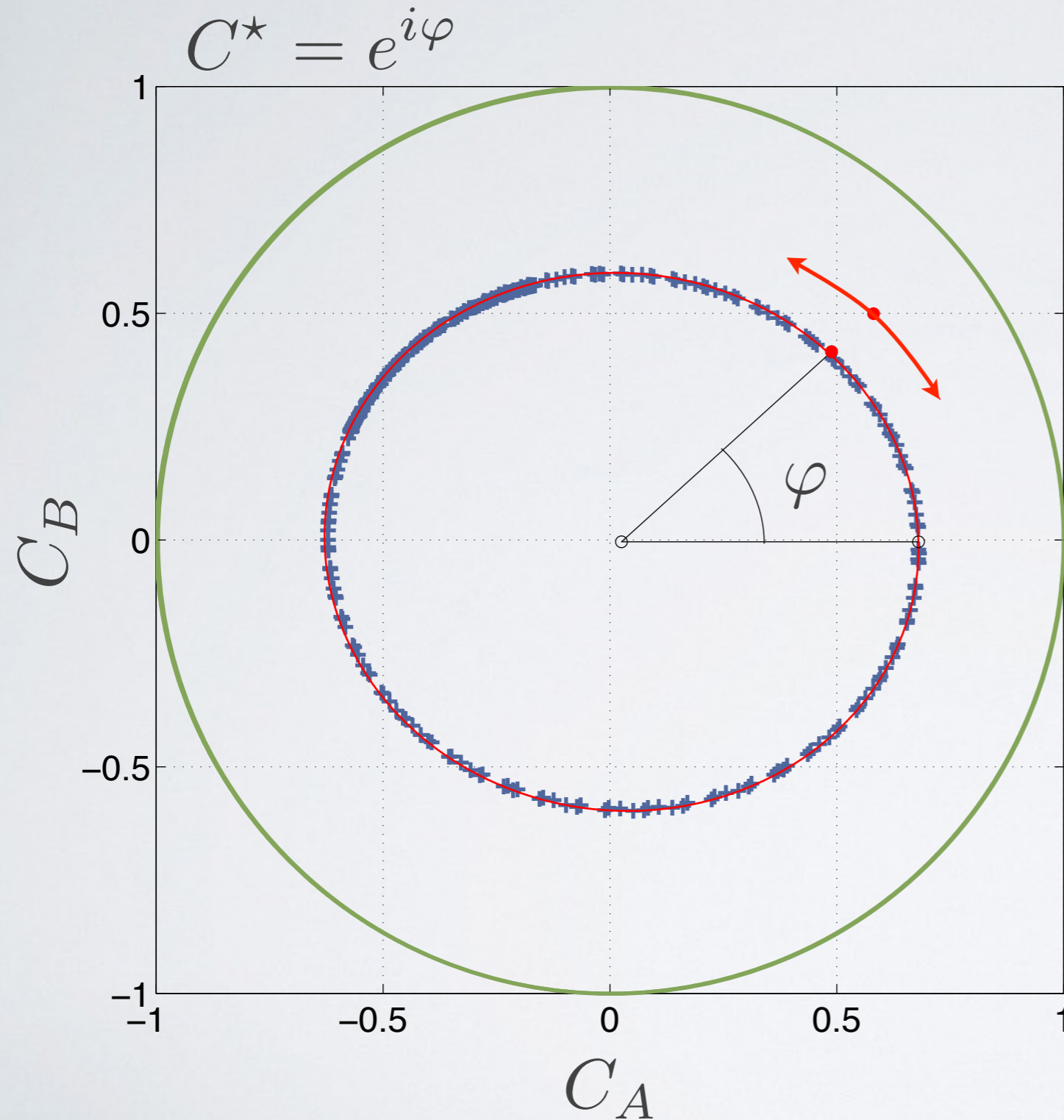


F. Ropars  
*Atelier électronique*

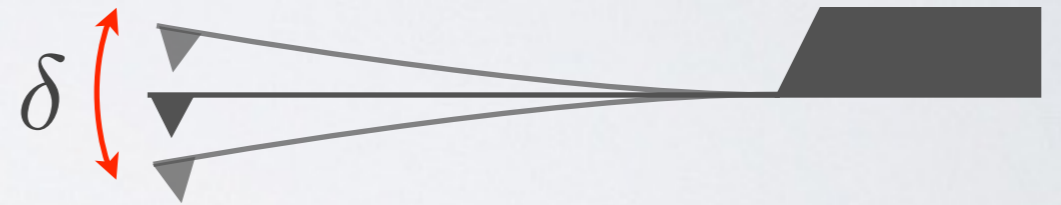


P. Paolino, F. Aguilar  
*Doctorants*

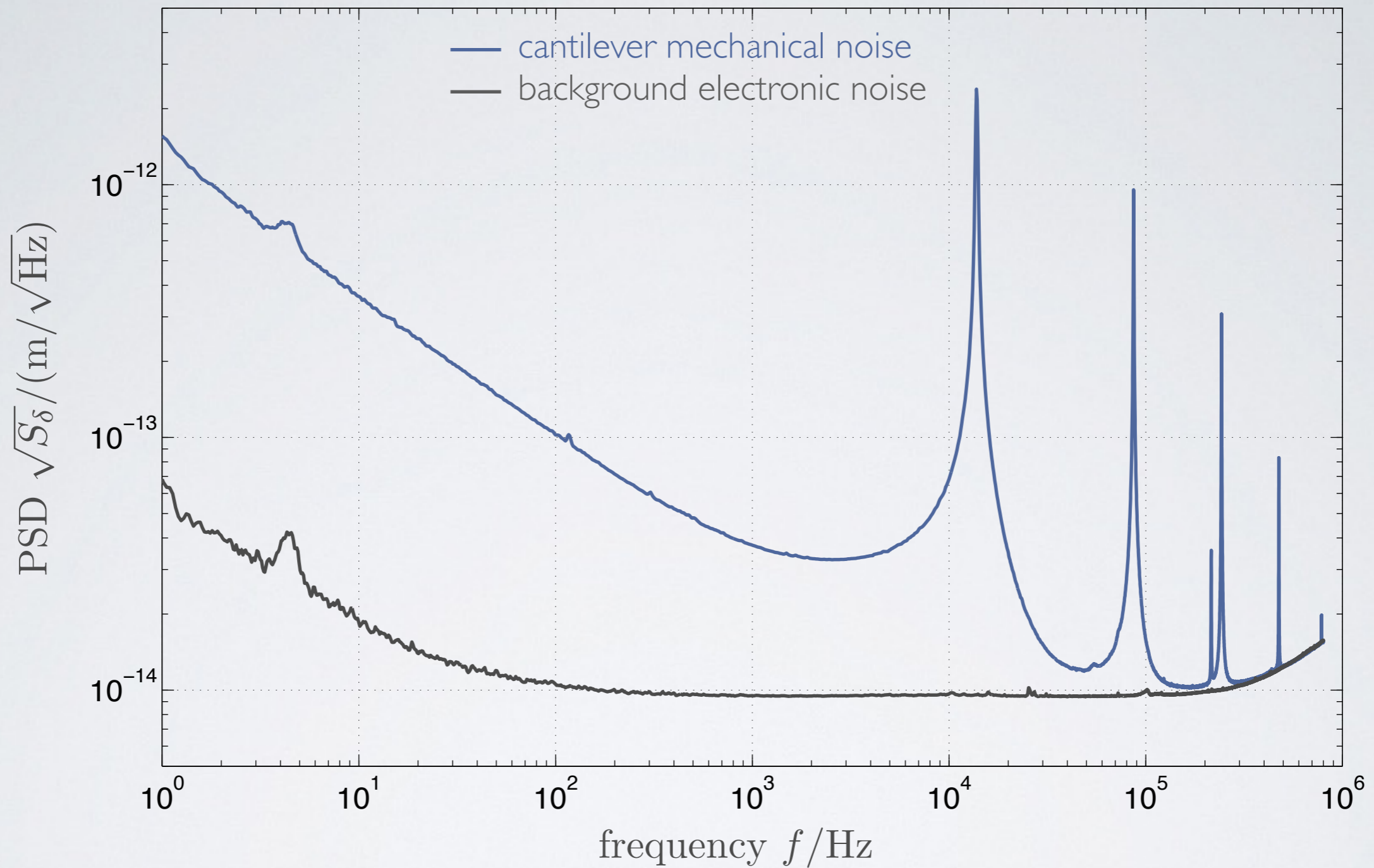




- + experimental data
- elliptic fit
- unit circle

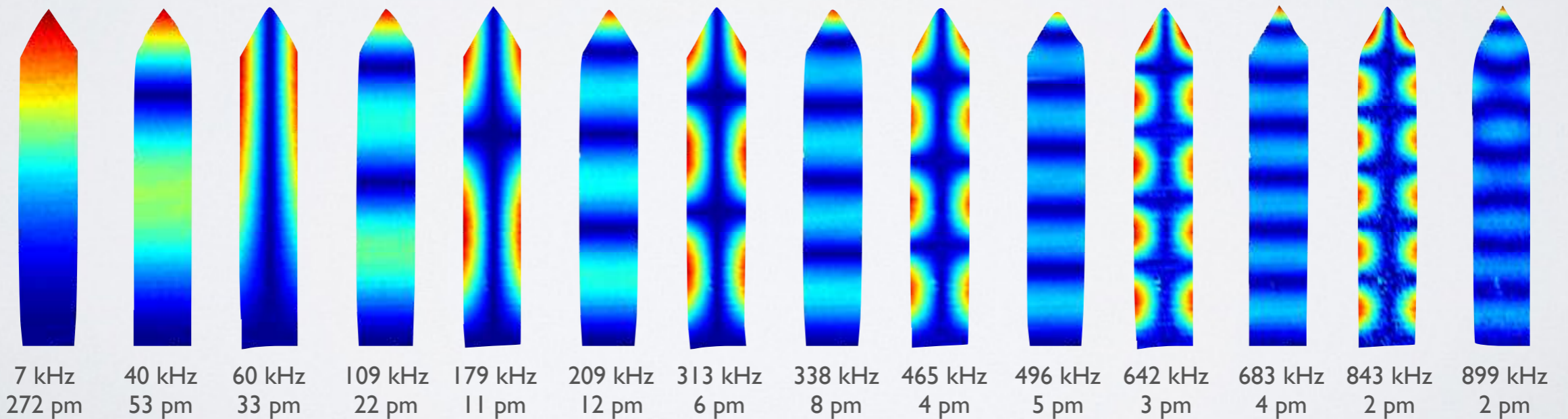
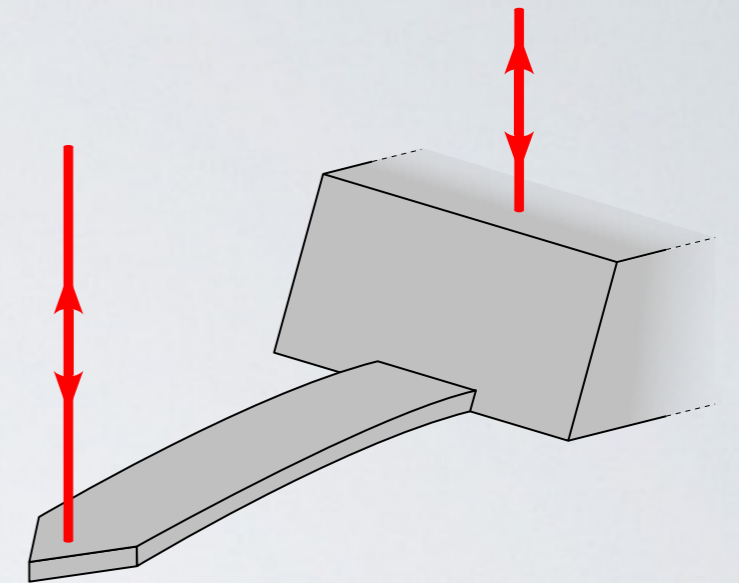
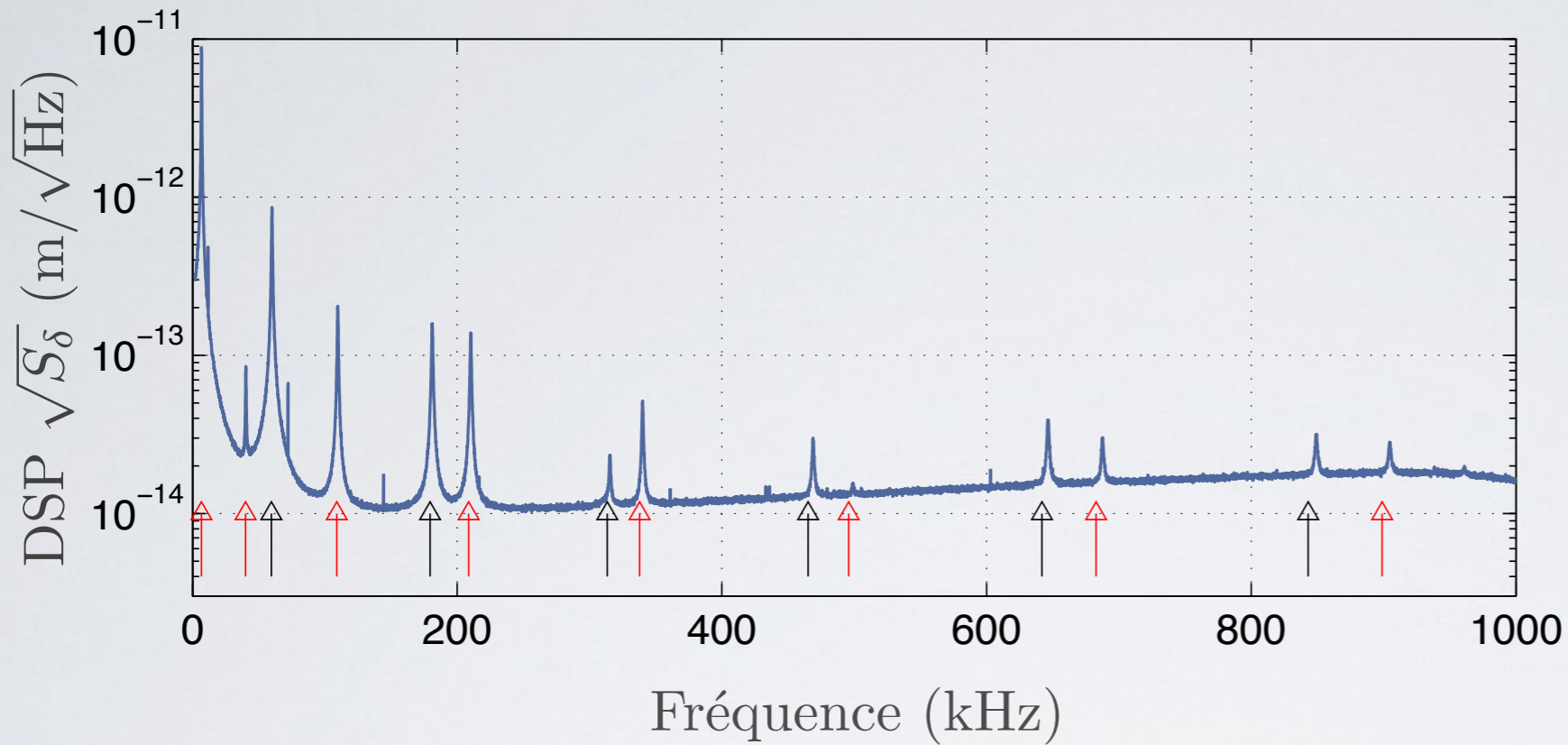


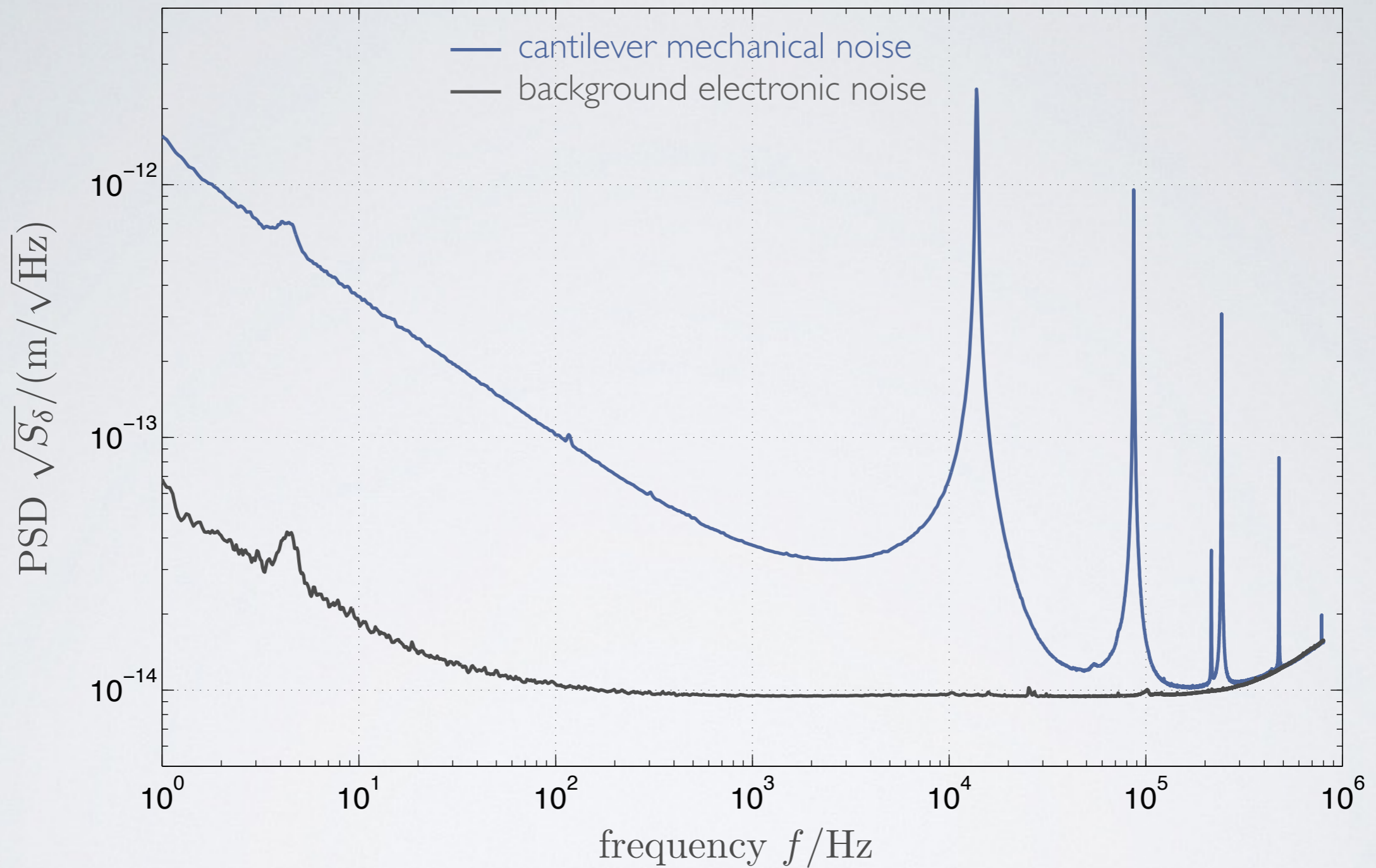
$$\varphi = \frac{2\pi}{\lambda} 2\delta$$



$$S_\delta(f) = \lim_{T \rightarrow \infty} \left\langle \frac{1}{2T} \left| \int_{-T}^T \delta(t) e^{i\omega t} dt \right|^2 \right\rangle \quad \langle \delta(t)^2 \rangle = \int_{\Delta f} S_\delta(f) df$$

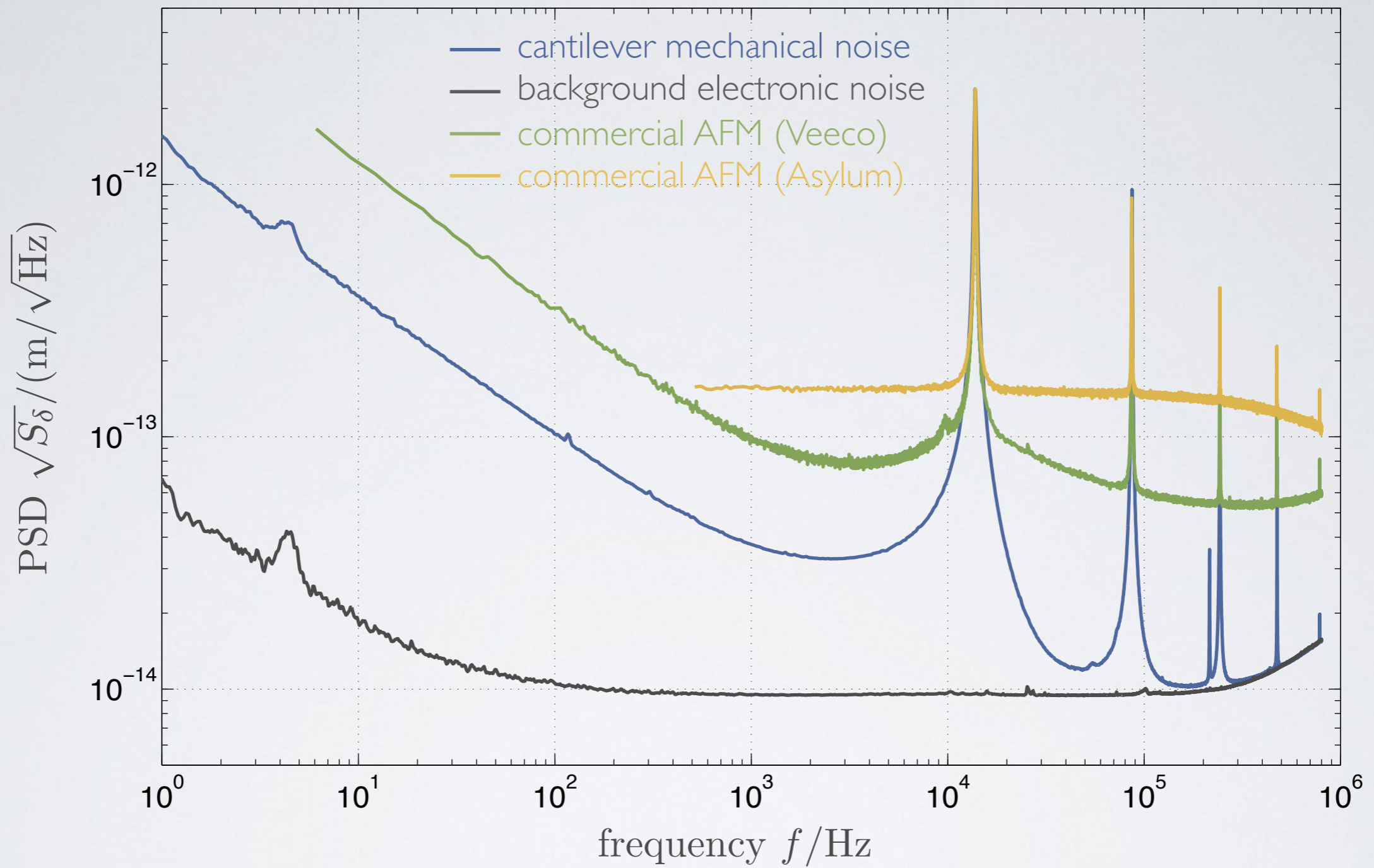
# Mapping of thermal fluctuations





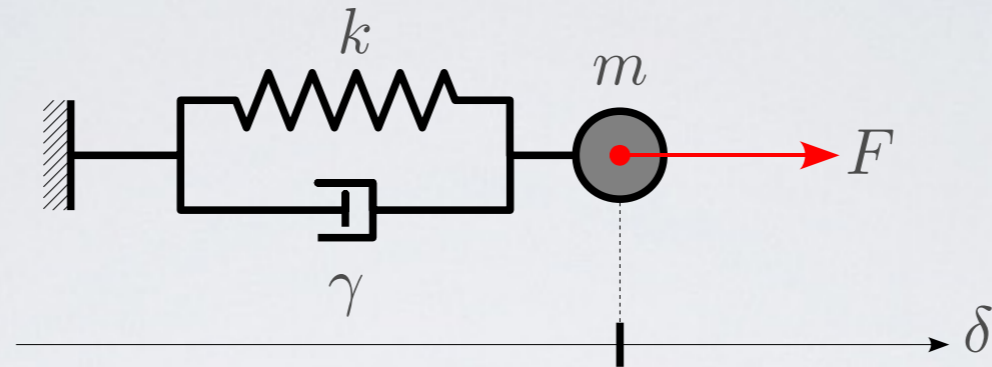
light power : 100  $\mu\text{W}$  - spot size : 5  $\mu\text{m}$

# Noise measurement





# Modeling noise : Sader model



$$m\ddot{\delta}(t) = -k\delta(t) - \gamma\dot{\delta}(t) + F(t)$$

Response function

$$G_{\text{SHO}}(\omega) = \frac{F(\omega)}{\delta(\omega)} = k - m\omega^2 + i\gamma\omega \longrightarrow G_{\text{Sader}}(\omega) = k - m_{\text{eff}}(\omega)\omega^2 + i\gamma_{\text{eff}}(\omega)\omega$$

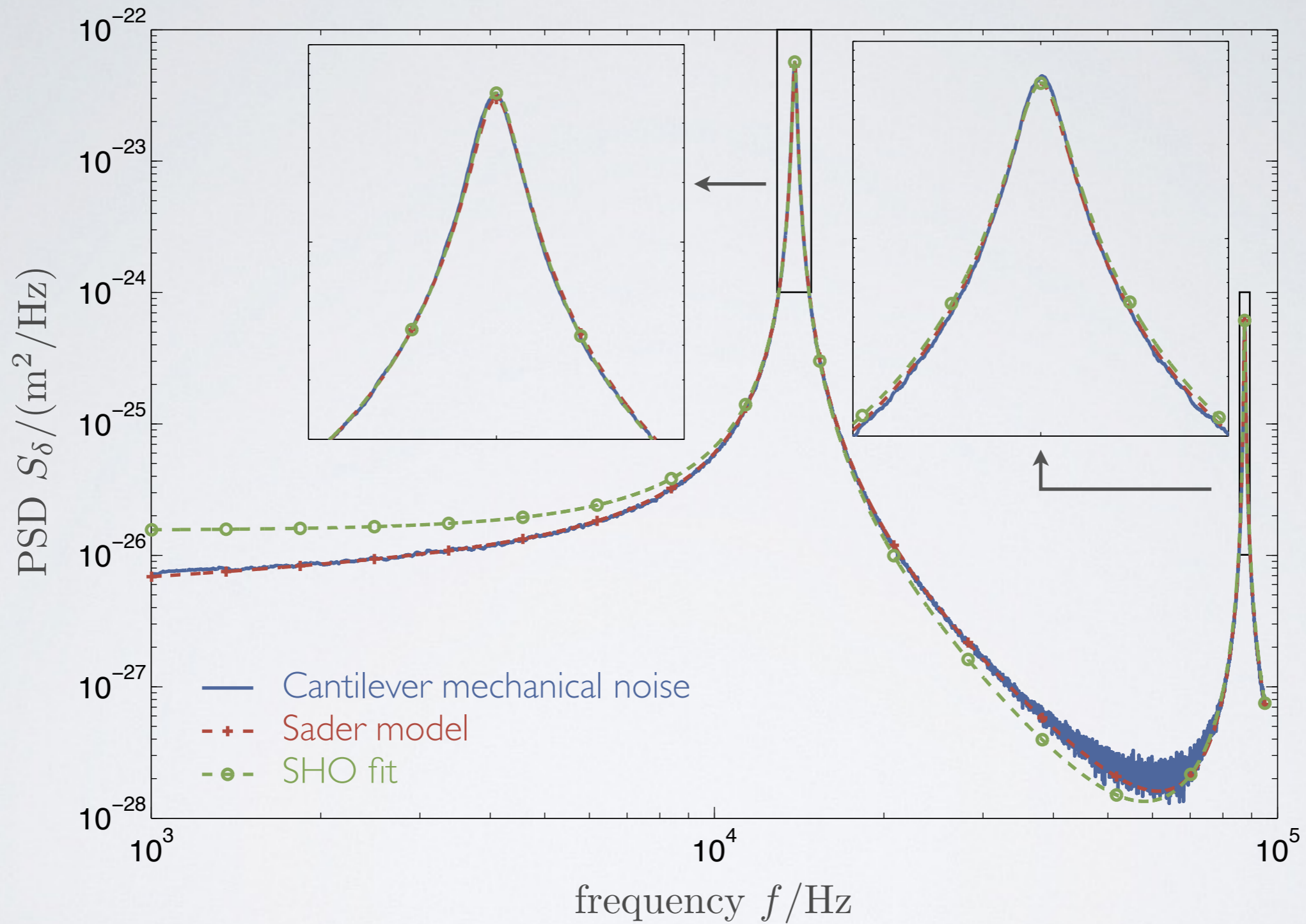
SHO model

Hydrodynamic loading model

Fluctuation-dissipation theorem

$$S_{\delta}(\omega) = -\frac{2k_B T}{\pi\omega} \text{Im} \left[ \frac{1}{G_{\text{Sader}}(\omega)} \right] = \frac{2k_B T}{\pi} \frac{\gamma_{\text{eff}}}{(k - m_{\text{eff}}\omega^2)^2 + (\gamma_{\text{eff}}\omega)^2}$$

# Modeling noise : SHO and Sader model



# From noise to response measurement

## Mechanical response

model response

$$G_{\text{Sader}}(\omega) = k - m_{\text{eff}}\omega^2 + i\gamma_{\text{eff}}\omega$$

**FDT**

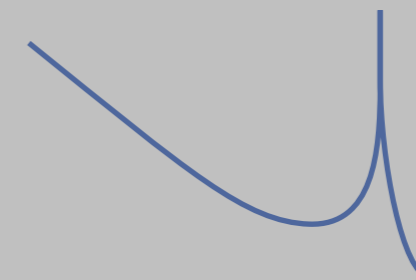
## Thermal noise spectrum

theoretical spectrum

$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G_{\text{Sader}}(\omega)} \right]$$

Compare

measured spectrum



# From noise to response measurement

## Mechanical response

model response

$$G_{\text{Sader}}(\omega) = k - m_{\text{eff}}\omega^2 + i\gamma_{\text{eff}}\omega$$

**FDT**

## Thermal noise spectrum

theoretical spectrum

$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G_{\text{Sader}}(\omega)} \right]$$

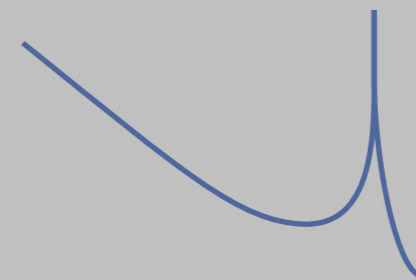
Compare

measured response

$$\text{Im} \left[ \frac{1}{G(\omega)} \right]$$

**FDT<sup>-1</sup>**

measured spectrum



# From noise to response measurement

## Mechanical response

model response

$$G_{\text{Sader}}(\omega) = k - m_{\text{eff}}\omega^2 + i\gamma_{\text{eff}}\omega$$

**FDT**

measured response

$$G(\omega) \xleftarrow{\text{KK}} \text{Im} \left[ \frac{1}{G(\omega)} \right]$$

**FDT<sup>-1</sup>**

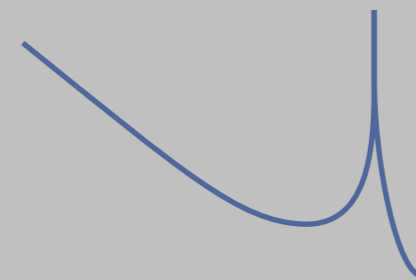
## Thermal noise spectrum

theoretical spectrum

$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G_{\text{Sader}}(\omega)} \right]$$

Compare

measured spectrum



# From noise to response measurement

## Mechanical response

model response

$$G_{\text{Sader}}(\omega) = k - m_{\text{eff}}\omega^2 + i\gamma_{\text{eff}}\omega$$

**FDT**

## Thermal noise spectrum

theoretical spectrum

$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G_{\text{Sader}}(\omega)} \right]$$

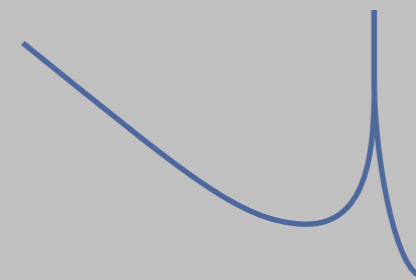
Compare

measured response

$$G(\omega) \leftarrow \text{KK} \text{Im} \left[ \frac{1}{G(\omega)} \right]$$

**FDT<sup>-1</sup>**

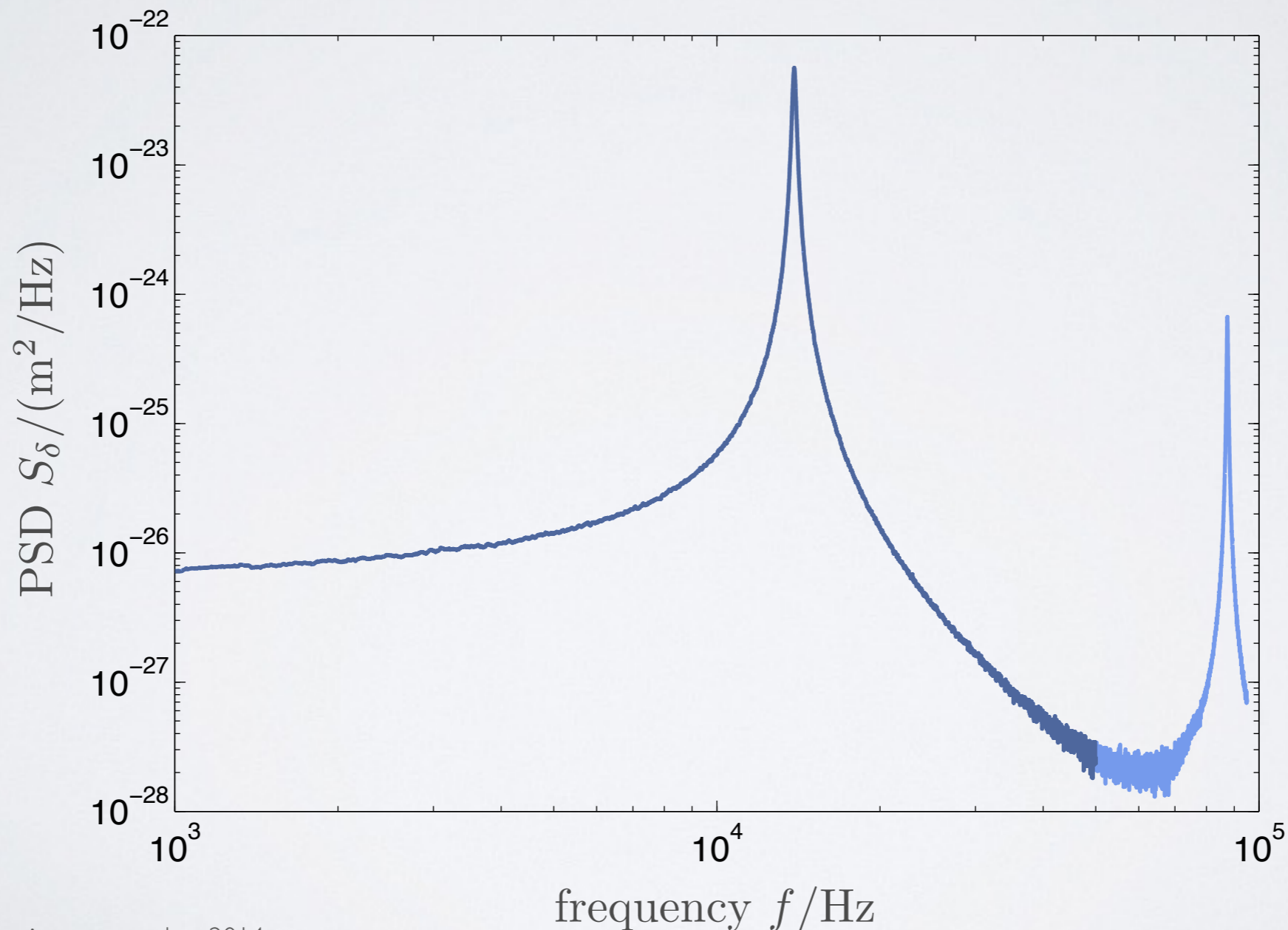
measured spectrum



# From noise to response measurement

$$\text{FDT : } \text{Im} \left[ \frac{1}{G(\omega)} \right] = -\frac{\omega}{4k_B T} S_\delta(\omega)$$

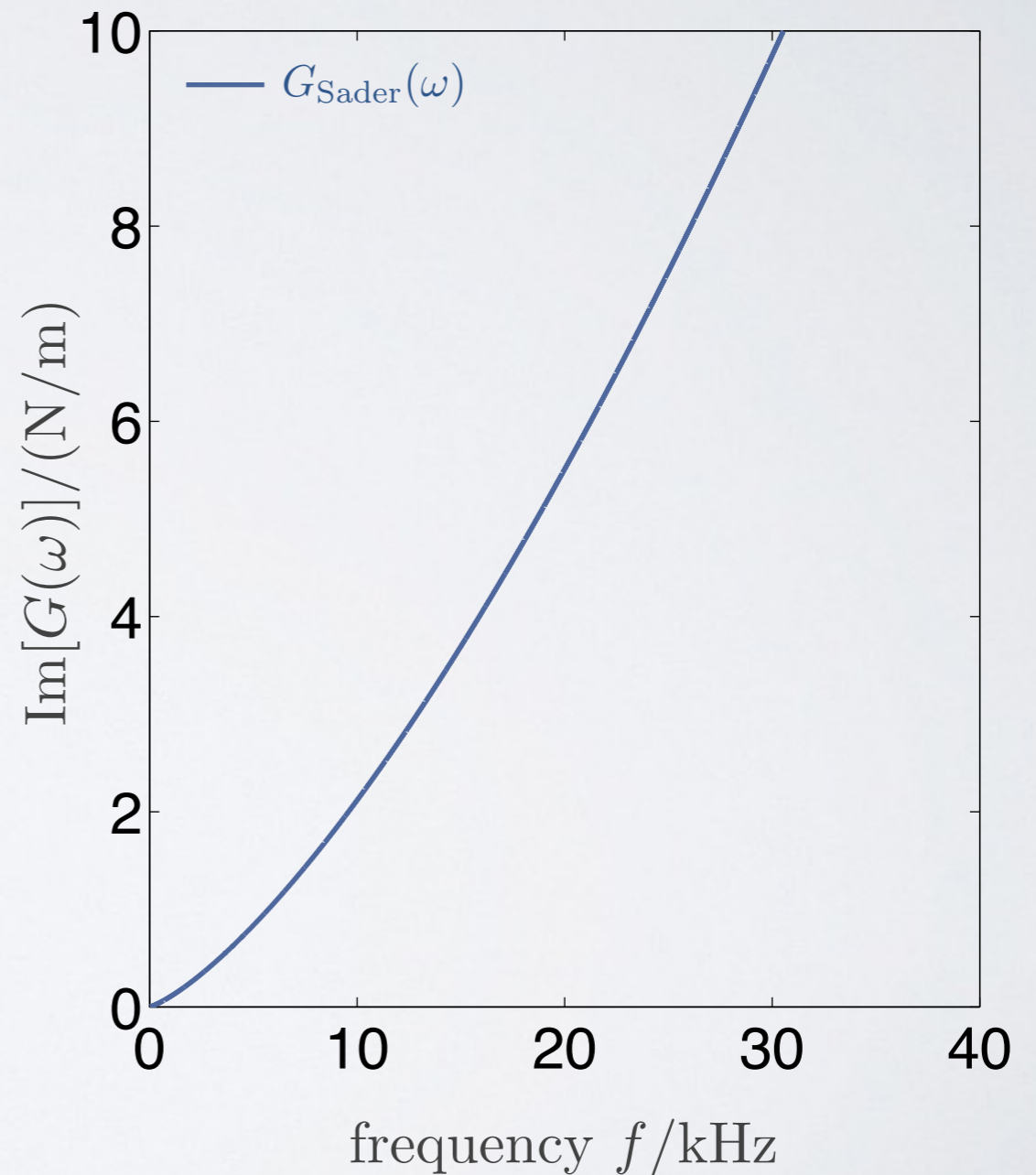
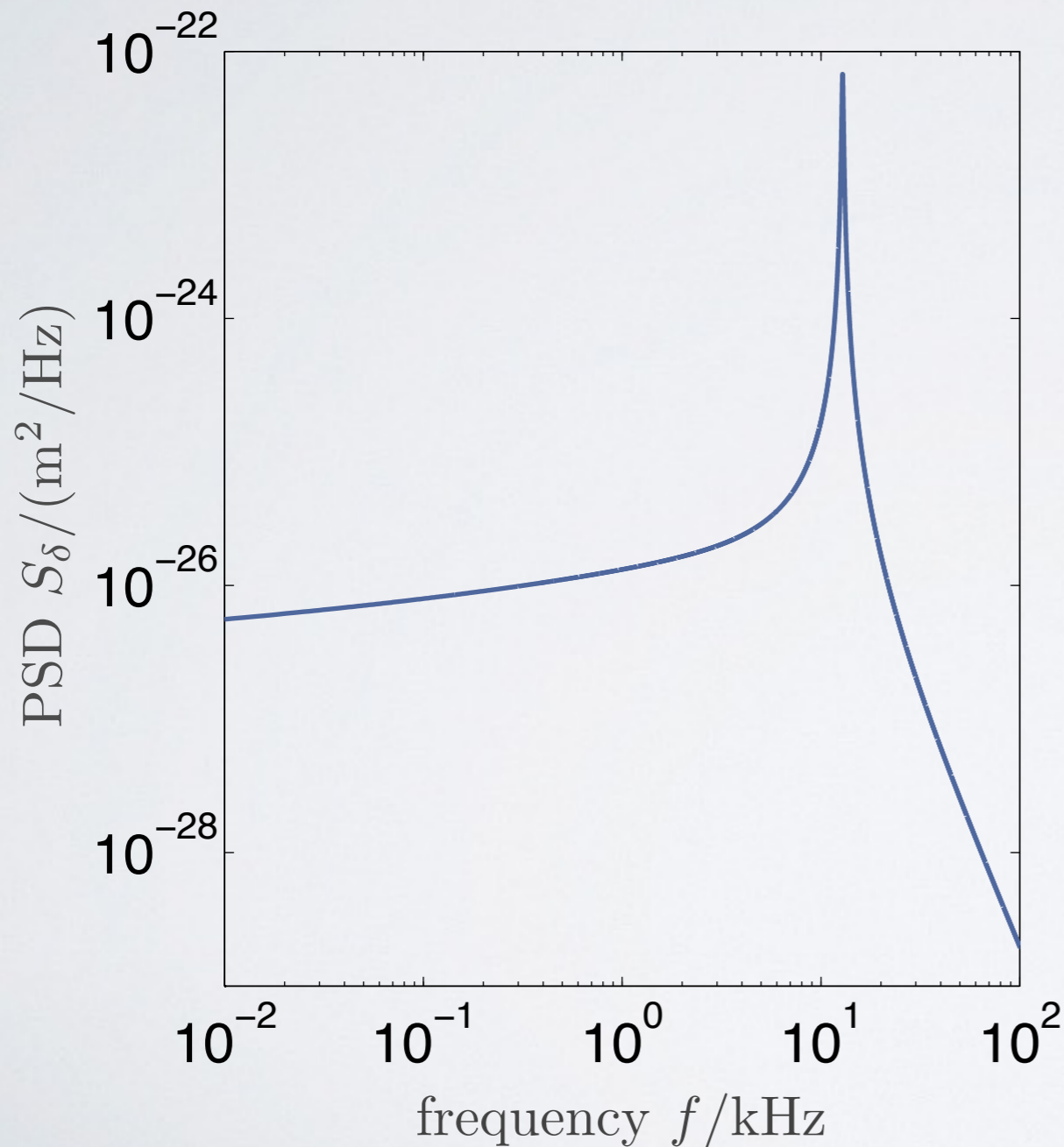
$$\text{Kramers-Kronig : } \text{Re} \left[ \frac{1}{G(\omega)} \right] = \frac{2}{\pi} \mathcal{P} \int_0^\infty \frac{\Omega}{\Omega^2 - \omega^2} \text{Im} \left[ \frac{1}{G(\omega)} \right] d\Omega$$



# Reconstruction of the full response

Synthetic signal : Sader model

$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G(\omega)} \right] \xleftarrow{\text{FDT}} G_{\text{Sader}}(\omega)$$

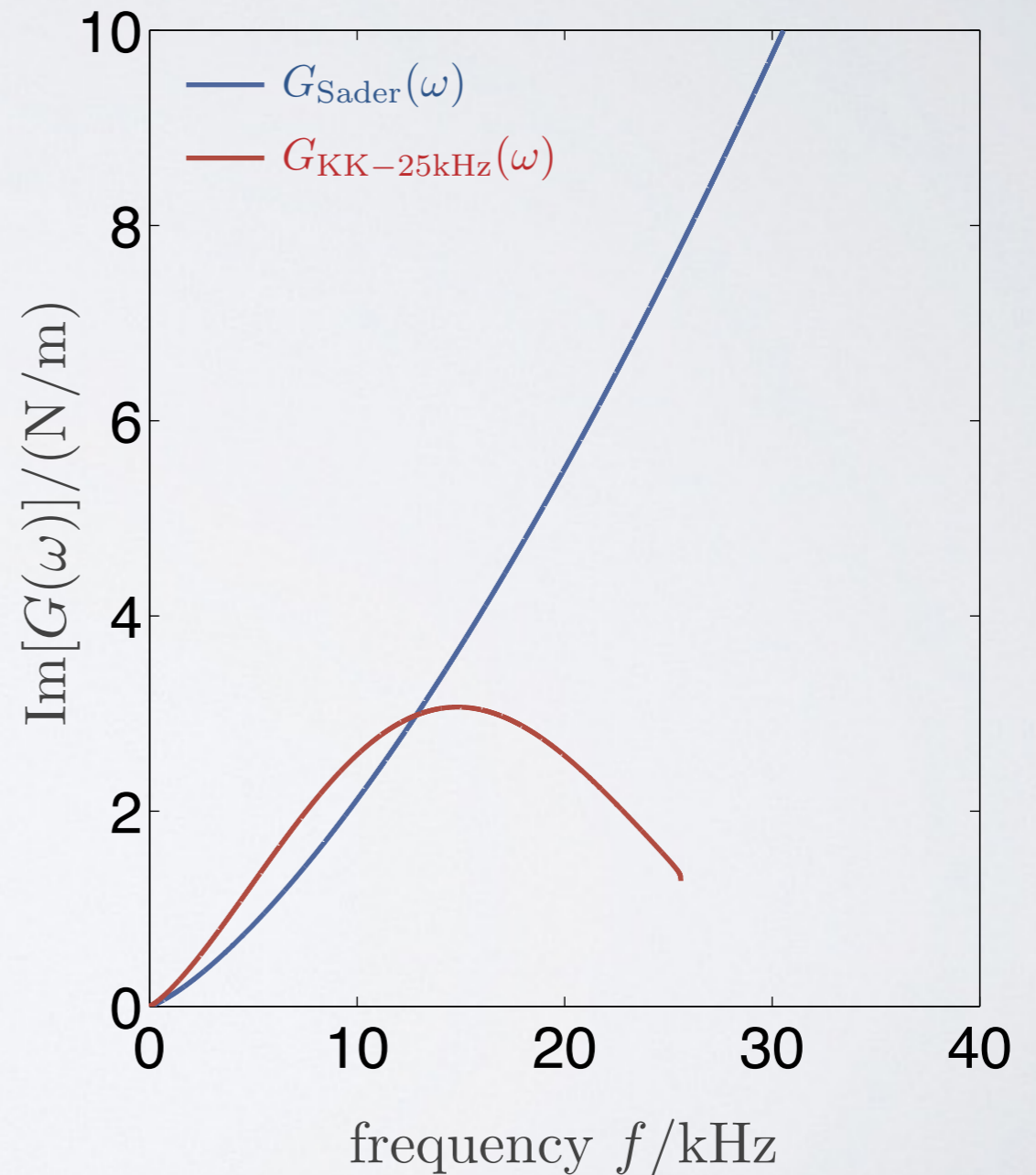
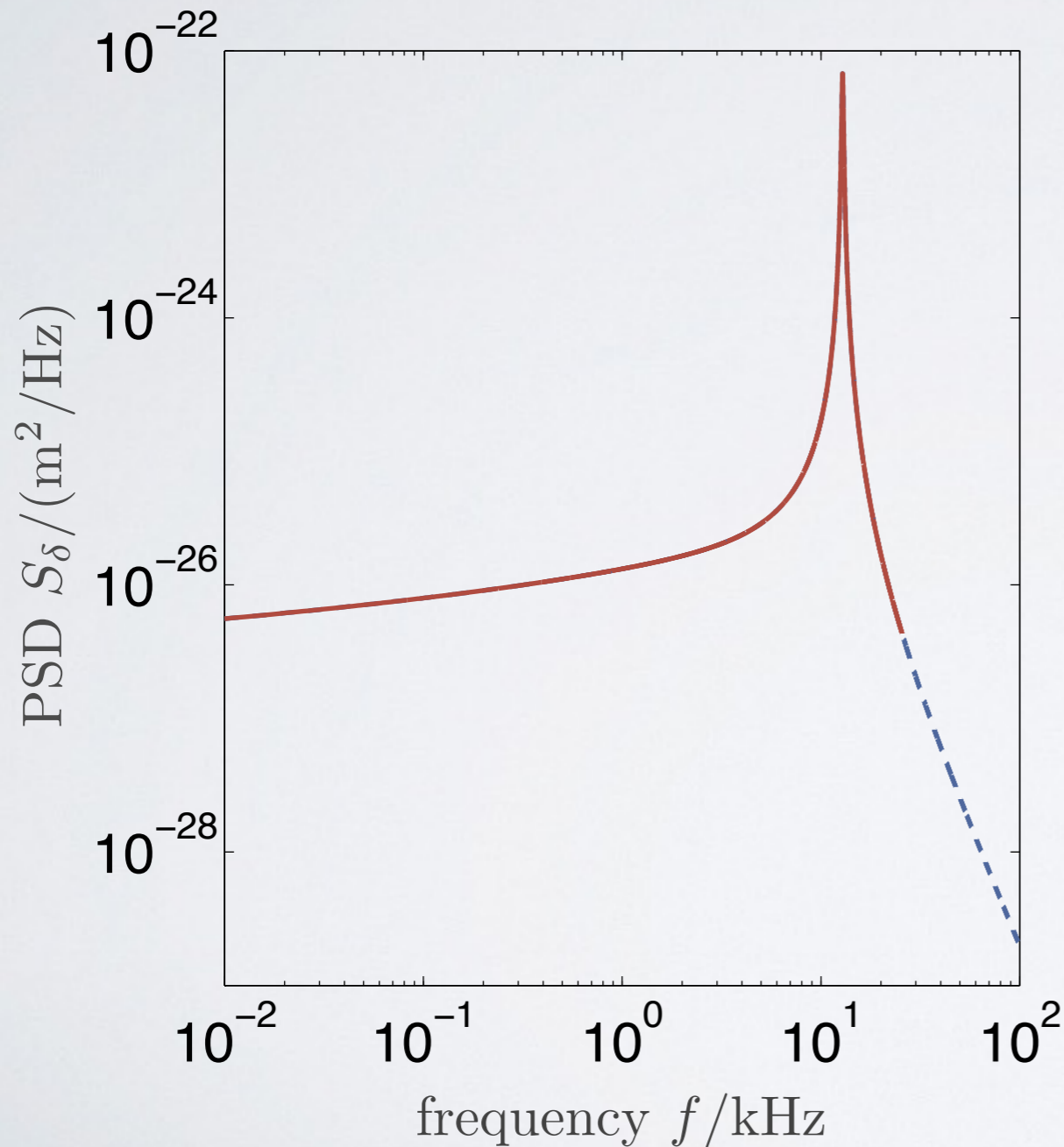




# Reconstruction of the full response

Synthetic signal : Sader model

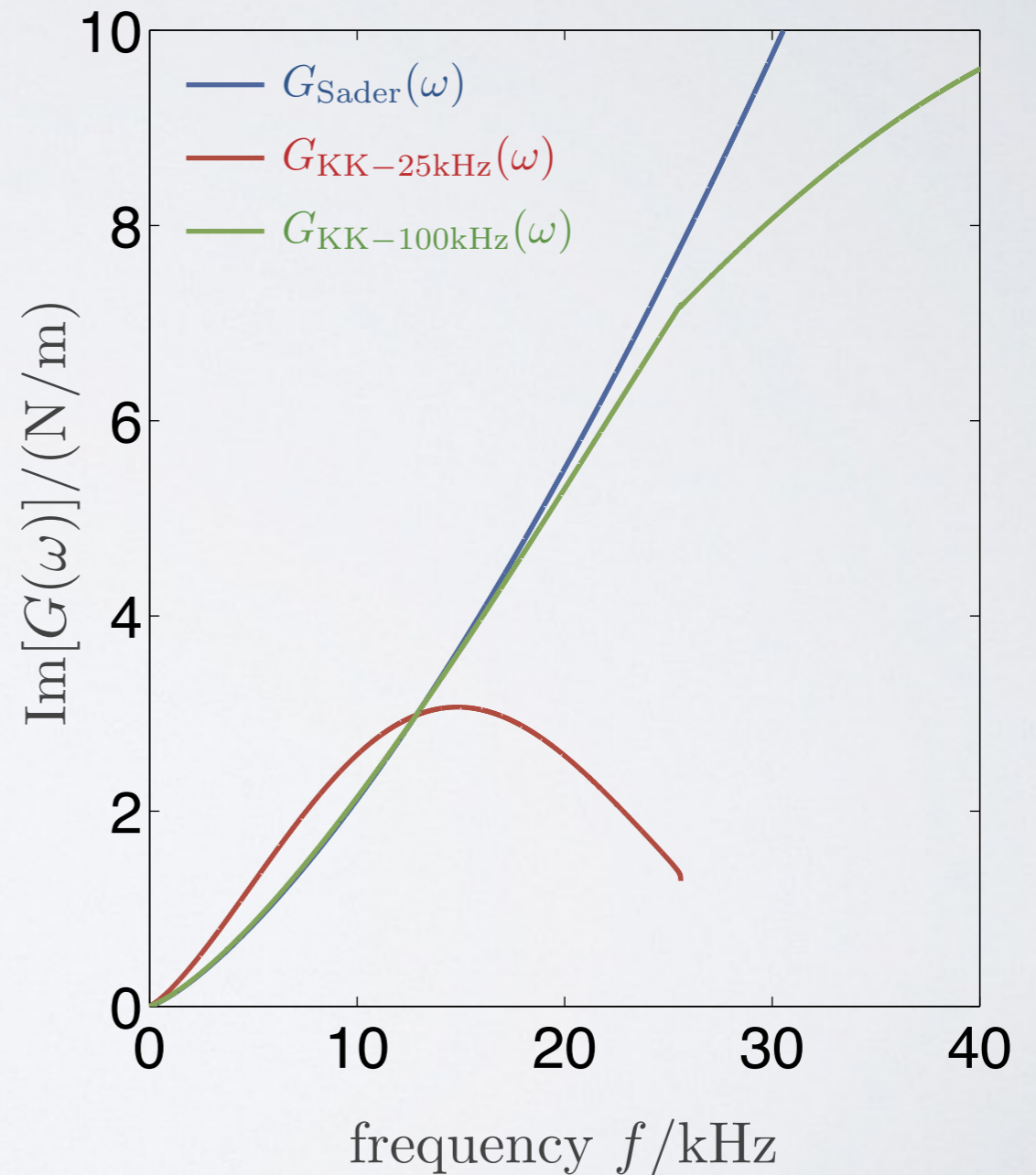
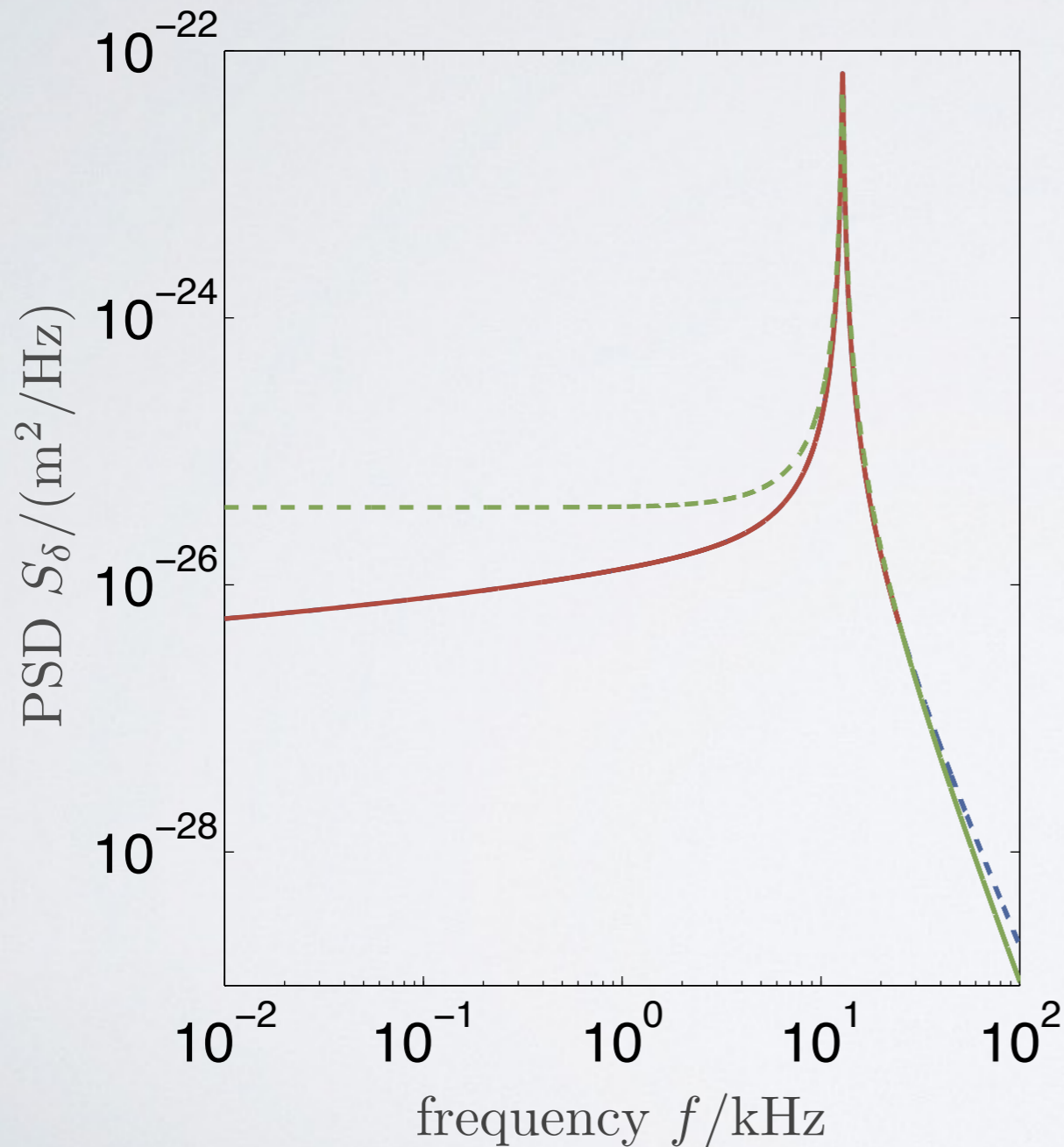
$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G(\omega)} \right] \xrightarrow{\text{KK}} \text{Re} \left[ \frac{1}{G(\omega)} \right] = \frac{2}{\pi} \mathcal{P} \int_0^{\infty} \frac{\Omega}{\Omega^2 - \omega^2} \text{Im} \left[ \frac{1}{G(\omega)} \right] d\Omega$$



# Reconstruction of the full response

Synthetic signal : Sader model

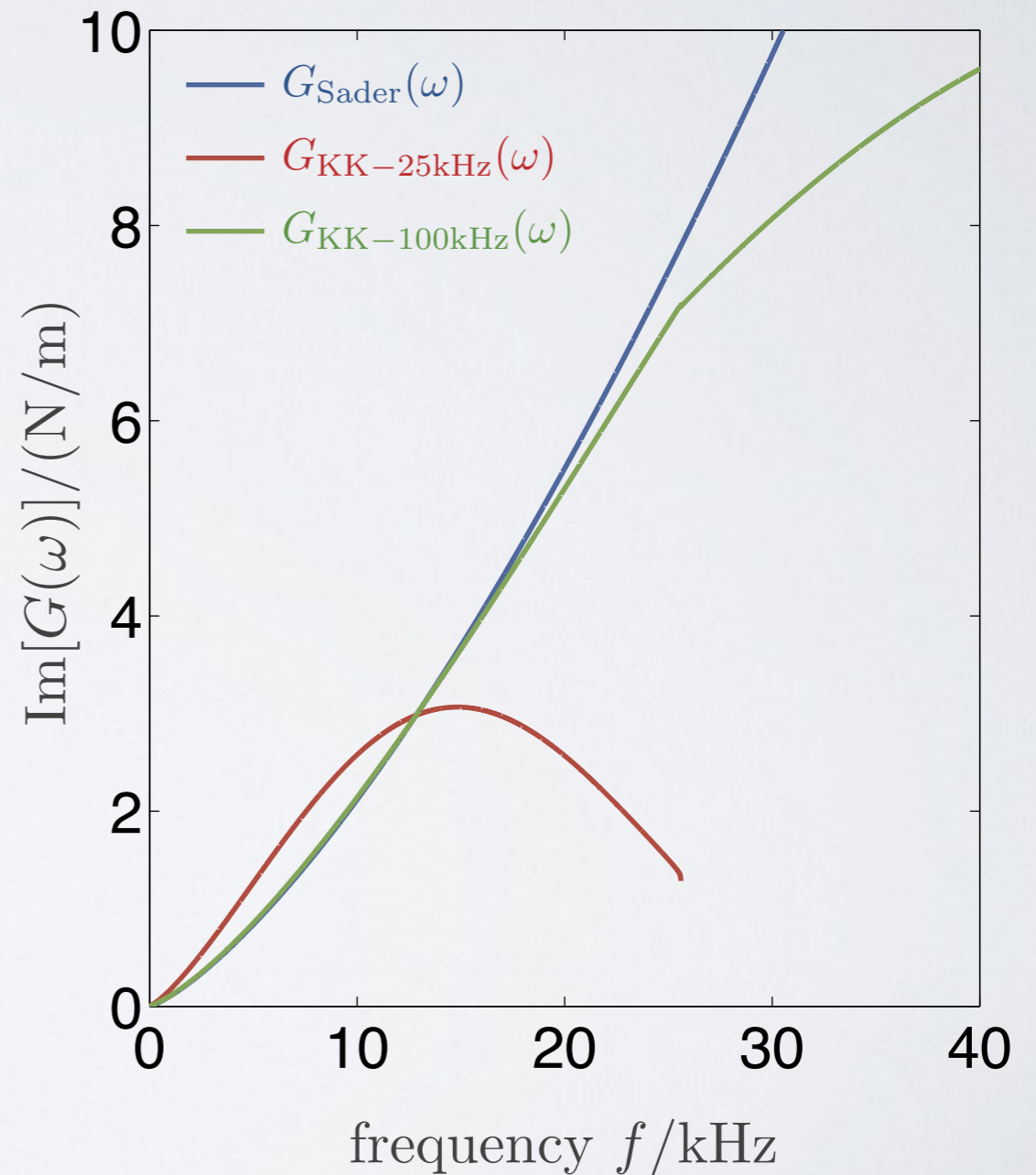
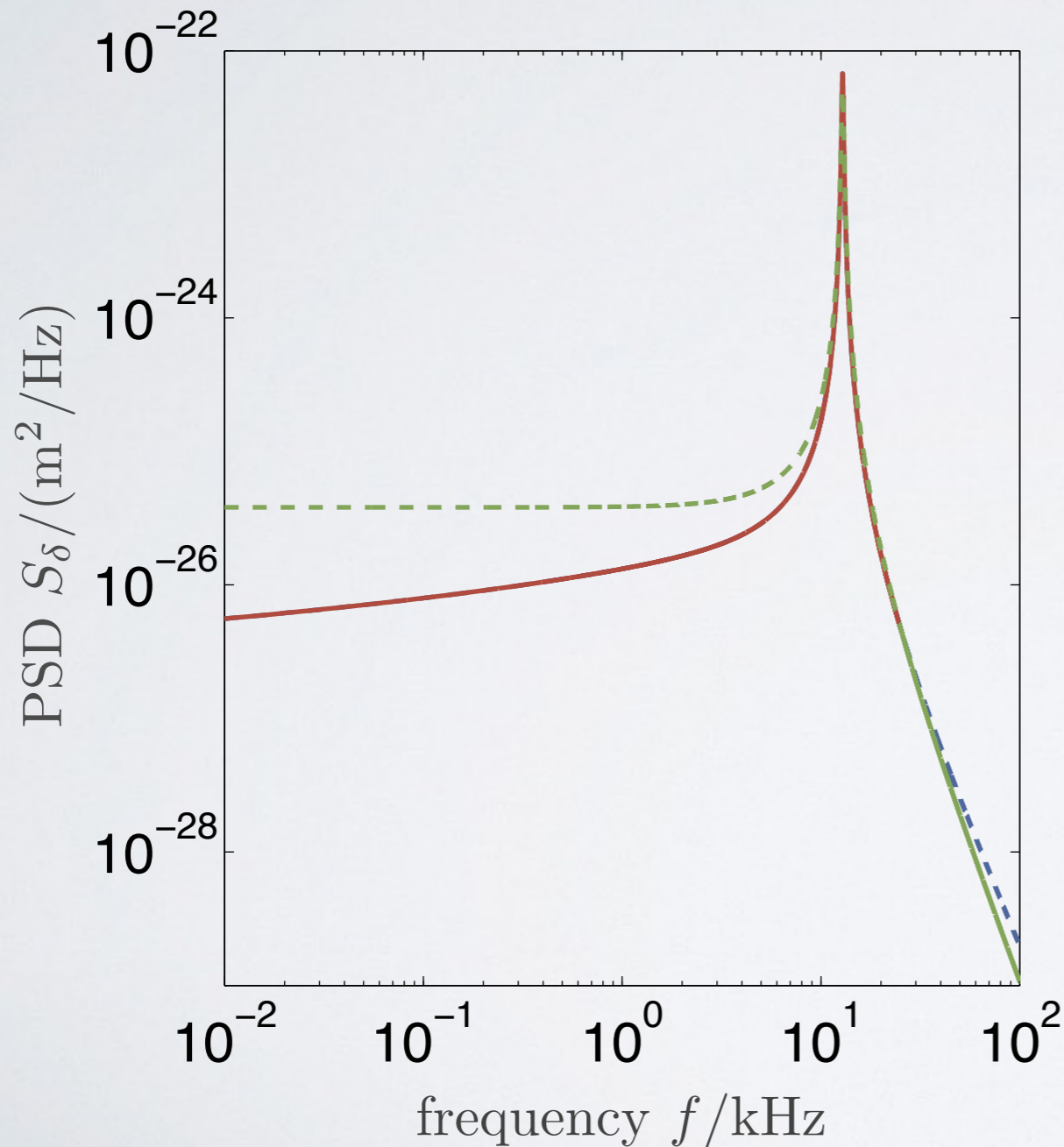
$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G(\omega)} \right] \xrightarrow{\text{KK}} \text{Re} \left[ \frac{1}{G(\omega)} \right] = \frac{2}{\pi} \mathcal{P} \int_0^{\infty} \frac{\Omega}{\Omega^2 - \omega^2} \text{Im} \left[ \frac{1}{G(\omega)} \right] d\Omega$$



# Reconstruction of the full response

Synthetic signal : Sader model

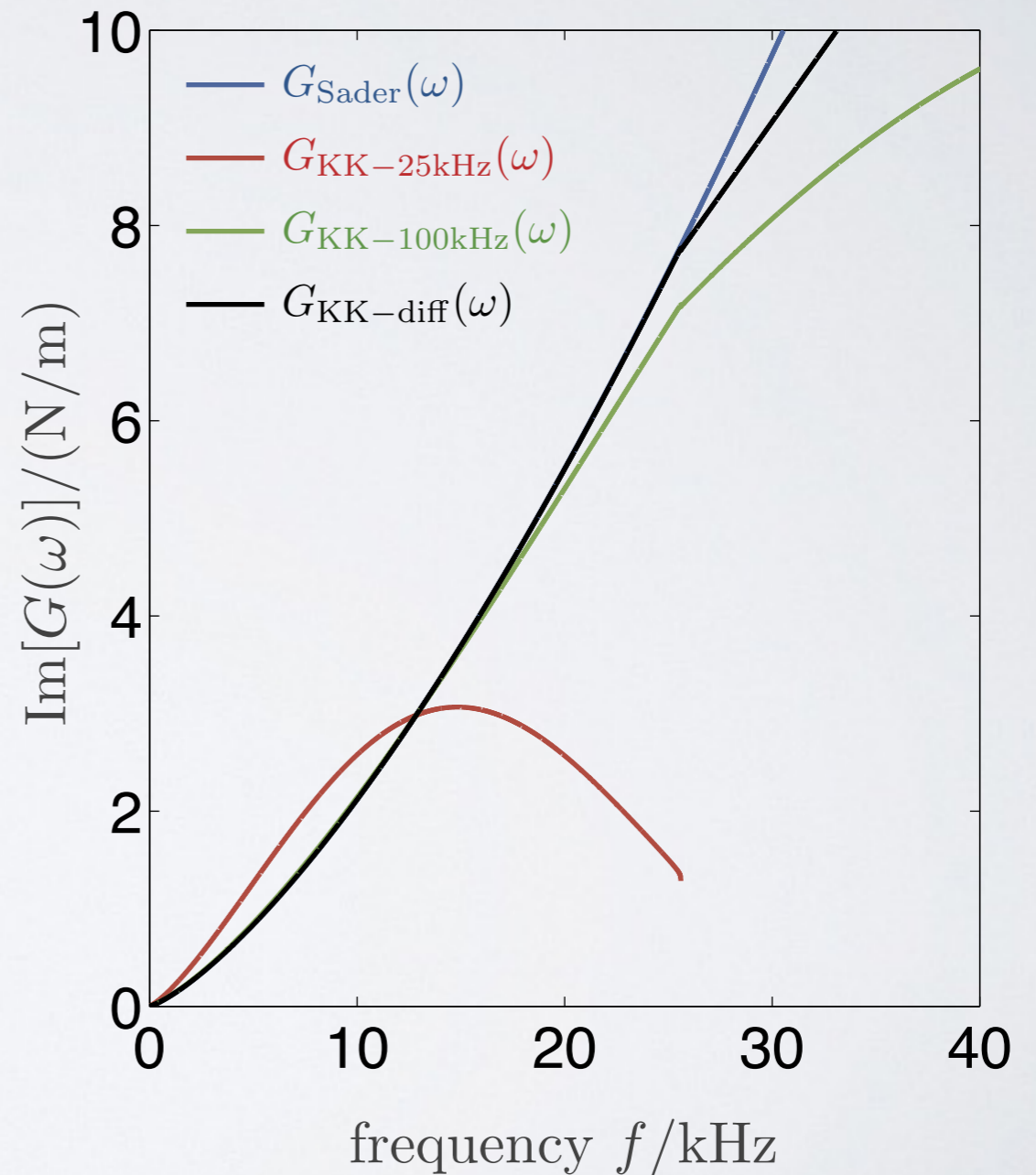
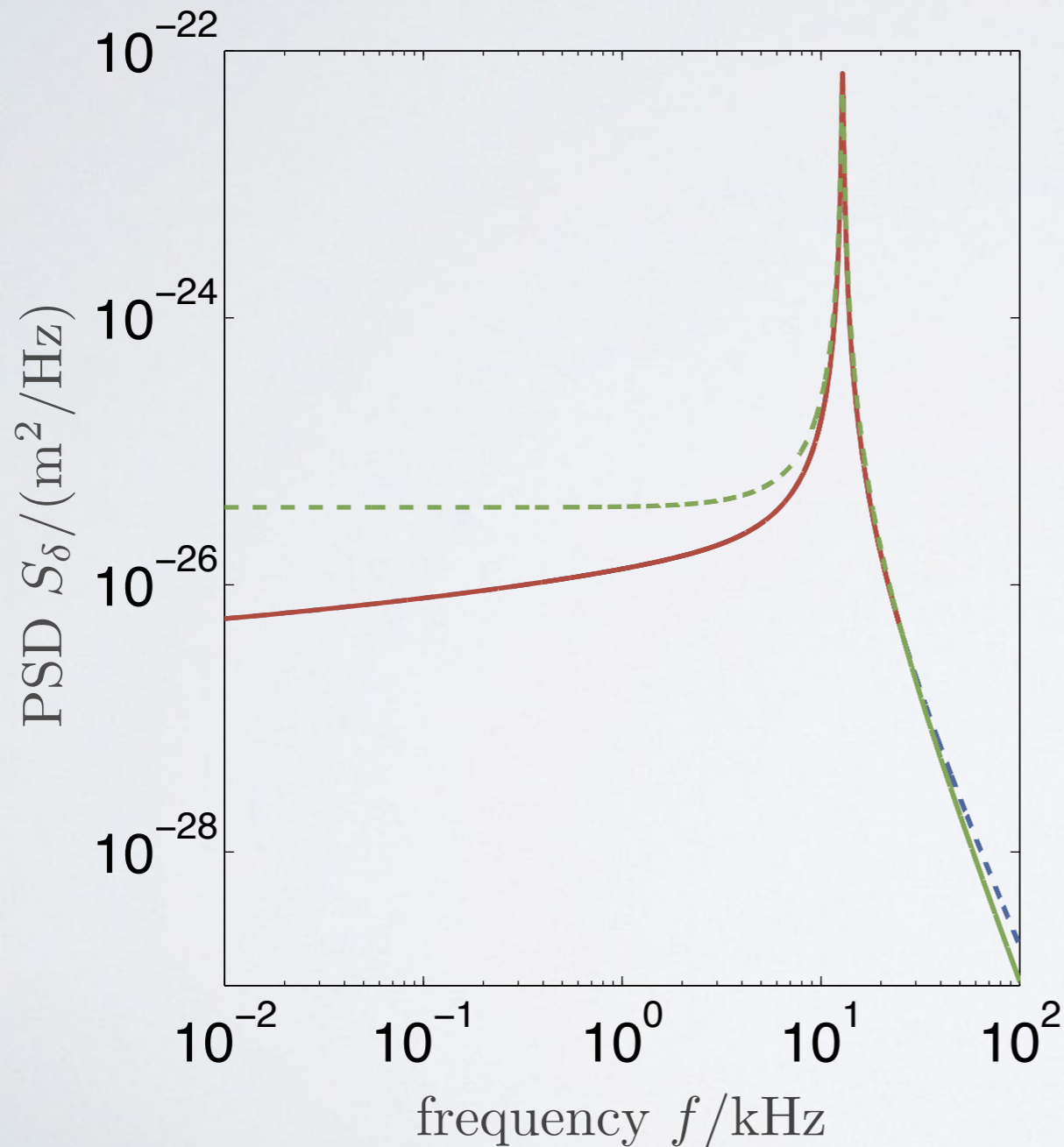
$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G(\omega)} \right] \xrightarrow{\text{KK}} \frac{1}{G(\omega)} = \text{KK} [S_{\delta}(\omega)]$$



# Reconstruction of the full response

Synthetic signal : Sader model

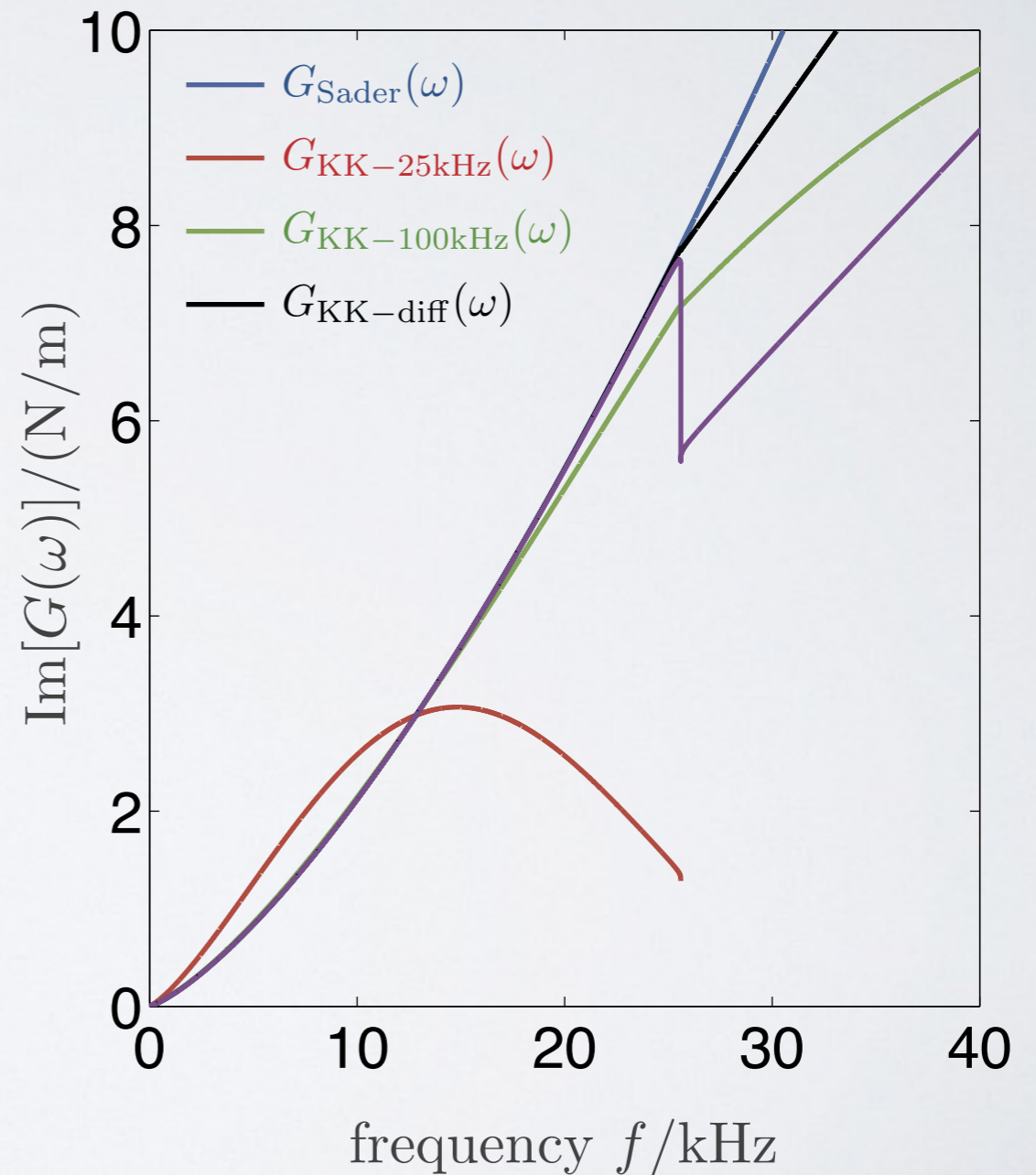
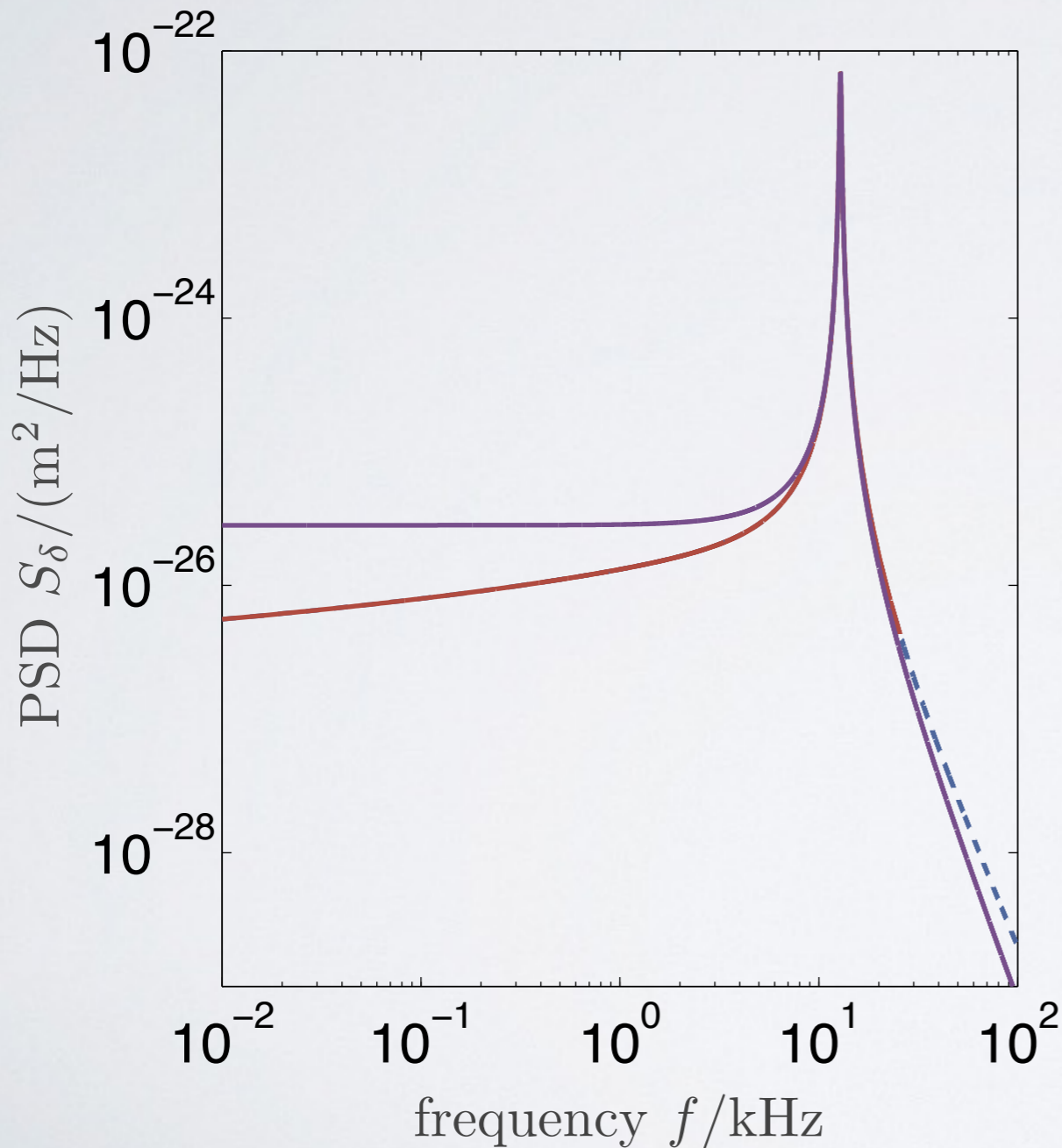
$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G(\omega)} \right] \xrightarrow{\text{KK}} \frac{1}{G(\omega)} - \frac{1}{G_0(\omega)} = \text{KK} [S_{\delta}(\omega) - S_{\delta 0}(\omega)]$$



# Reconstruction of the full response

Synthetic signal : Sader model

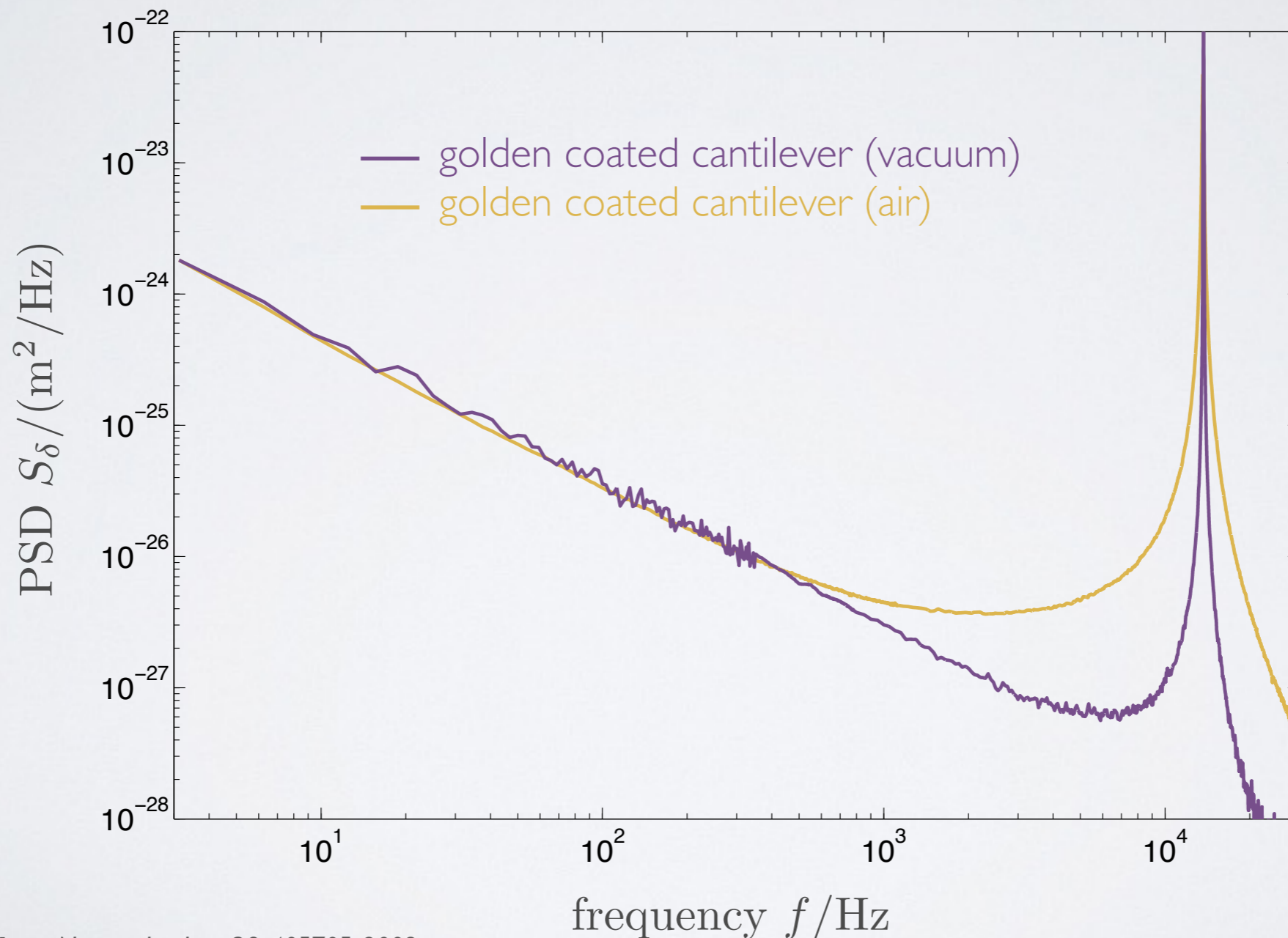
$$S_{\delta}(\omega) \propto \text{Im} \left[ \frac{1}{G(\omega)} \right] \xrightarrow{\text{KK}} \frac{1}{G(\omega)} - \frac{1}{G_0(\omega)} = \text{KK} [S_{\delta}(\omega) - S_{\delta_0}(\omega)]$$



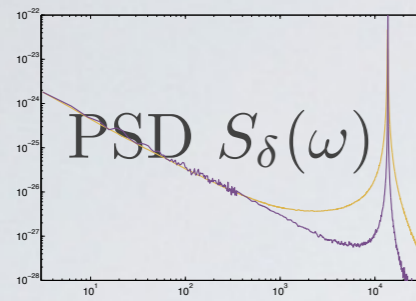
# Cantilever internal damping: 1/f noise ?

$$\text{FDT : } \text{Im} \left[ \frac{1}{G(\omega)} \right] = -\frac{\omega}{4k_B T} S_\delta(\omega)$$

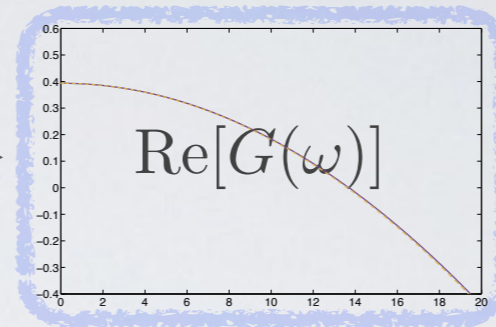
$$\text{Kramers-Kronig : } \text{Re} \left[ \frac{1}{G(\omega)} \right] = \frac{2}{\pi} \mathcal{P} \int_0^\infty \frac{\Omega}{\Omega^2 - \omega^2} \text{Im} \left[ \frac{1}{G(\omega)} \right] d\Omega$$



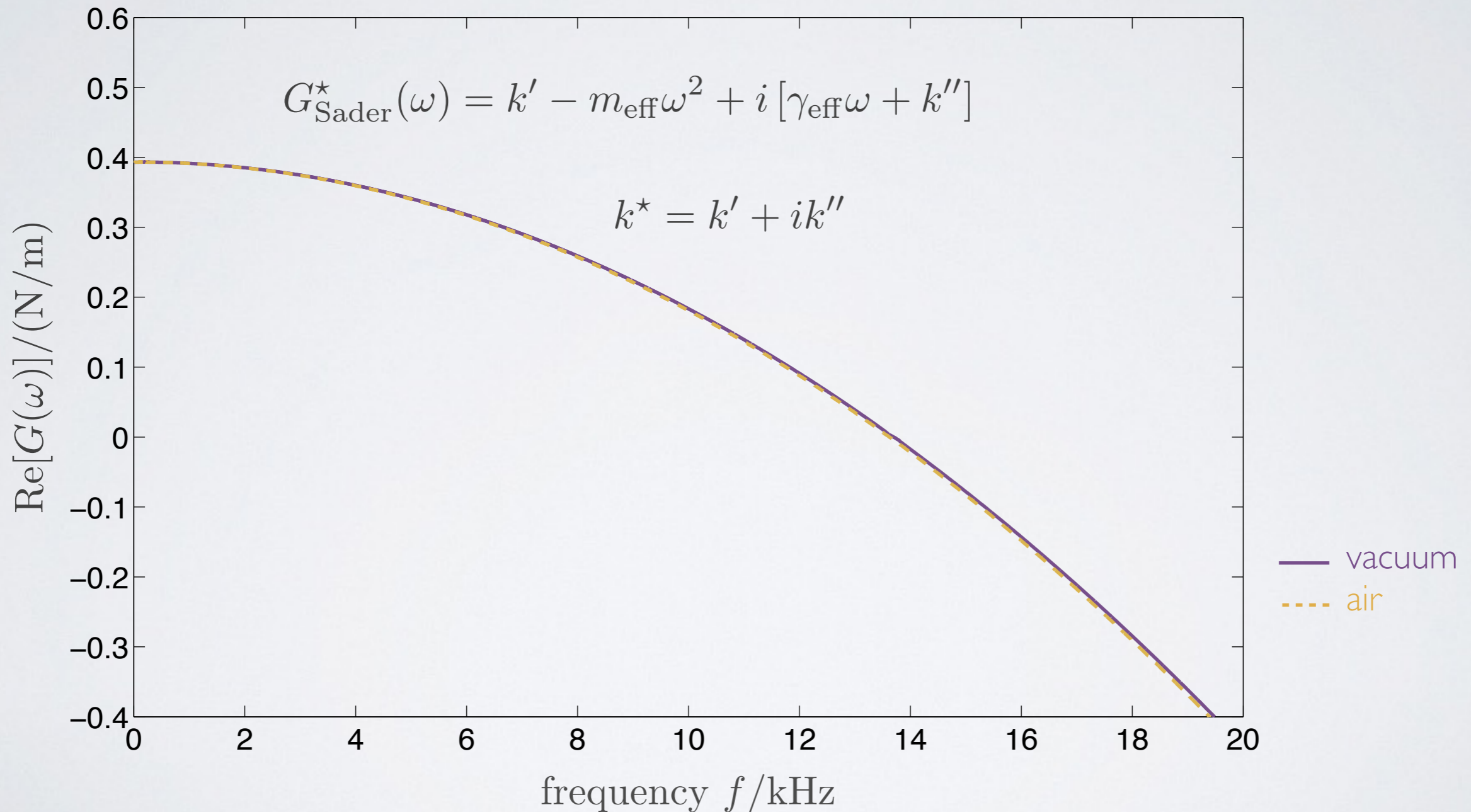
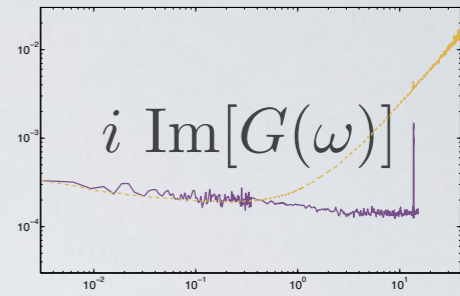
# Internal damping: mechanical response



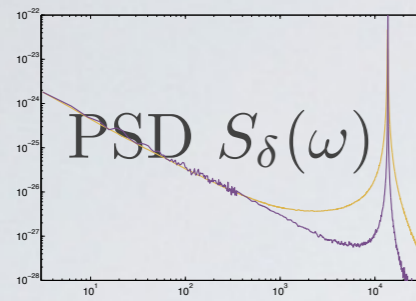
**FDT<sup>-1</sup> + KK**



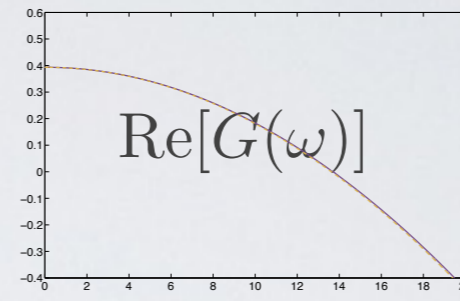
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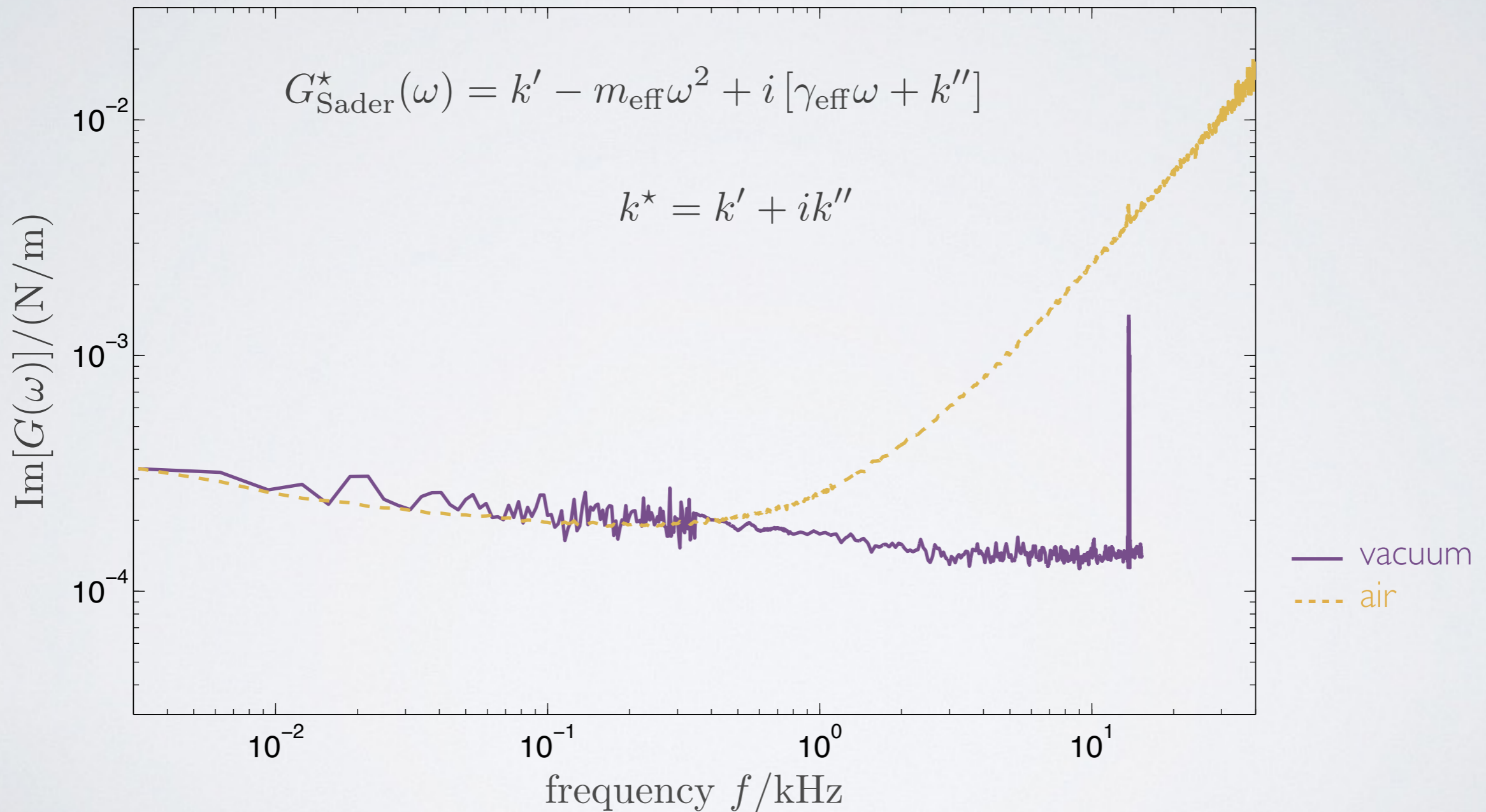
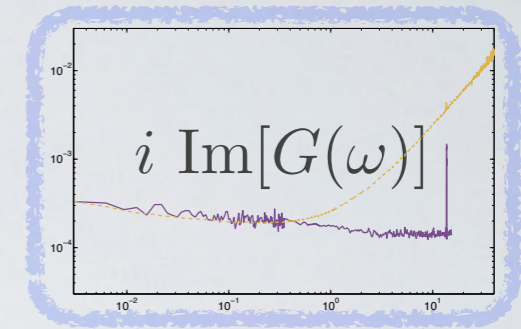
# Internal damping: mechanical response



**FDT<sup>-1</sup> + KK**

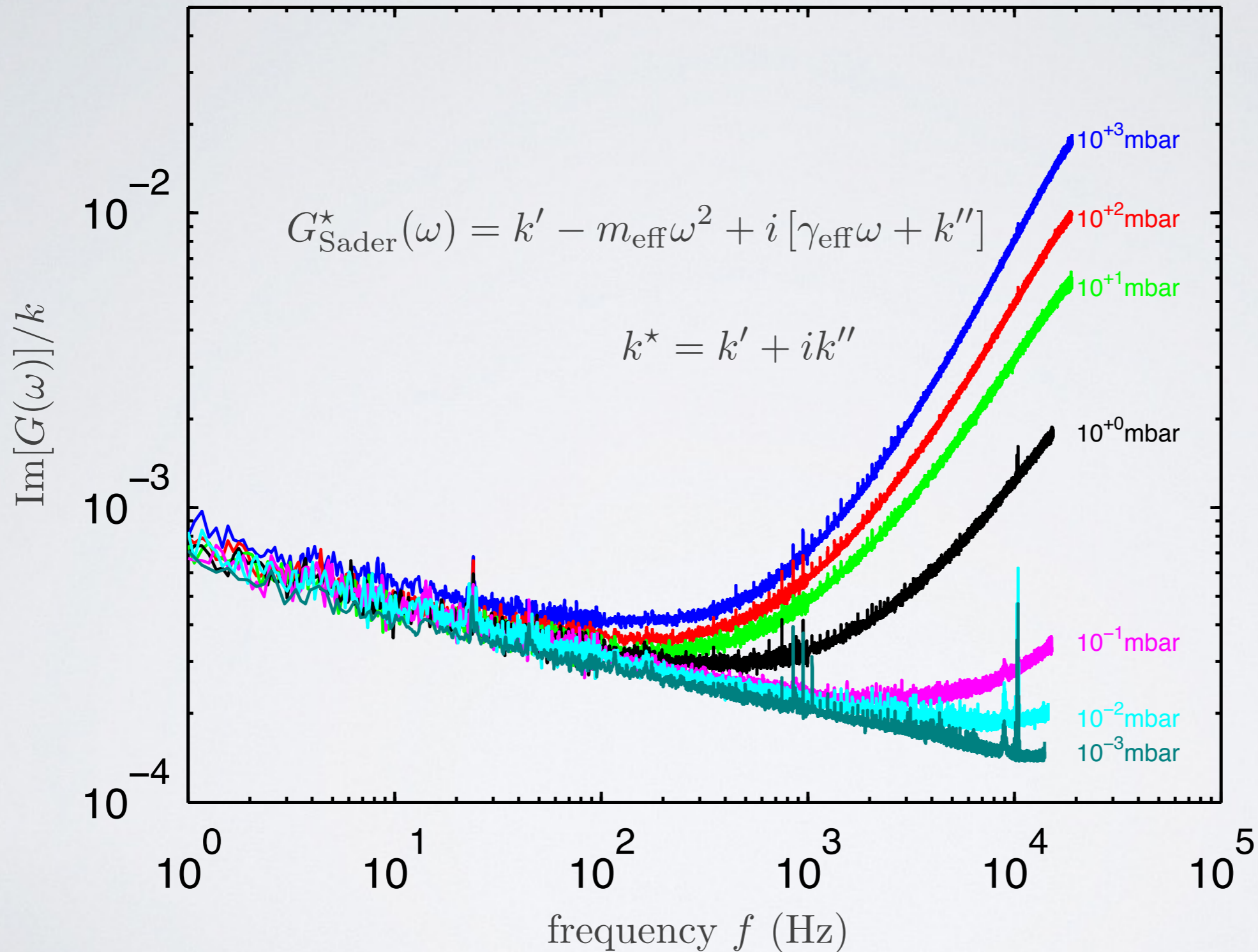


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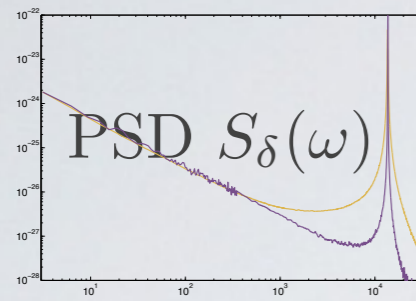




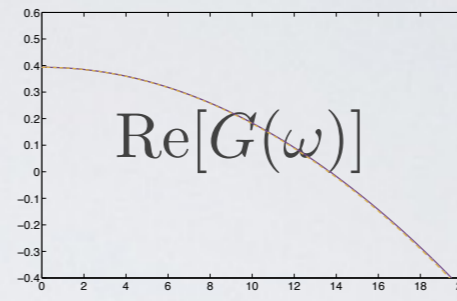
# Internal damping: viscoelasticity



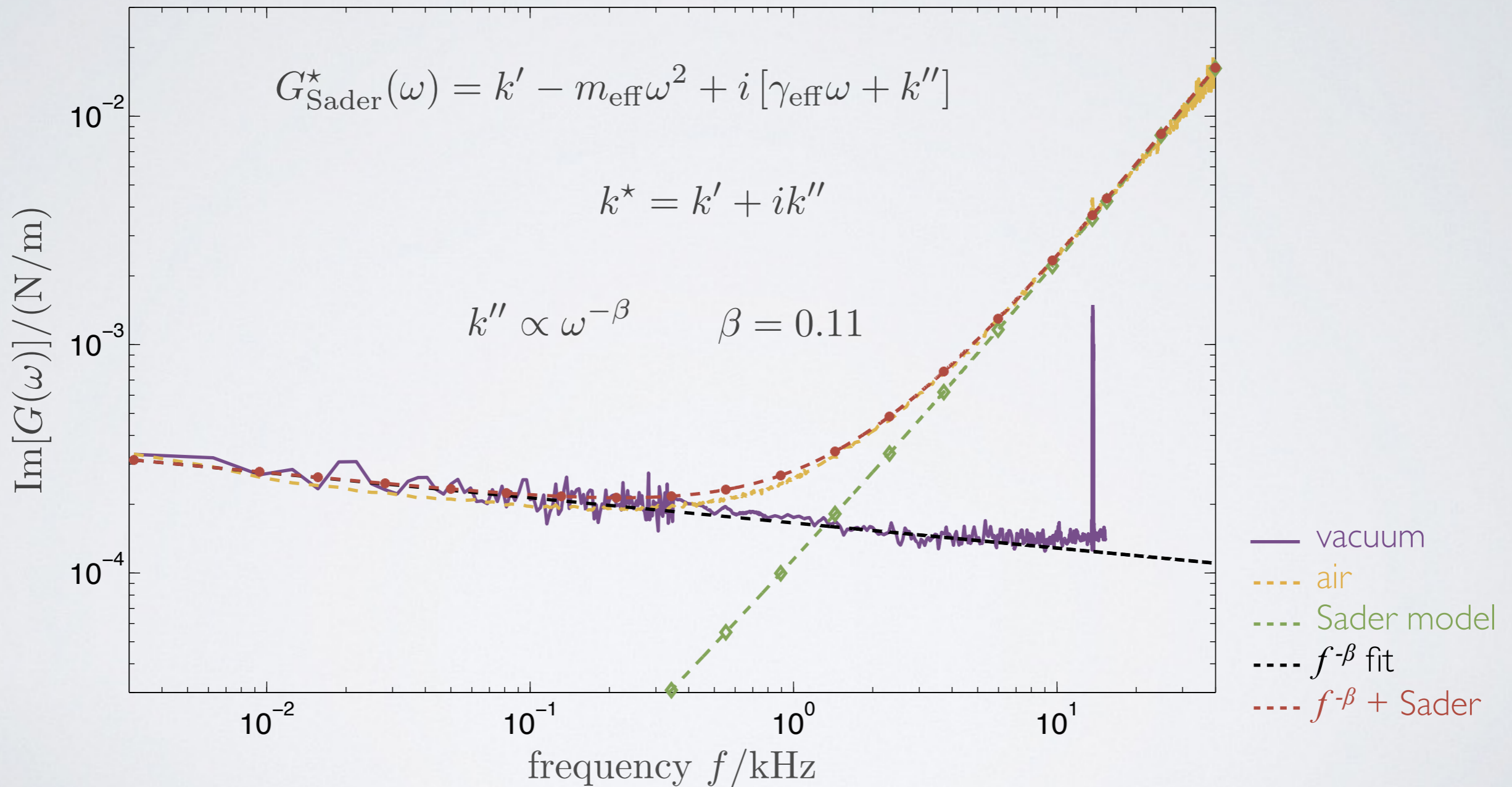
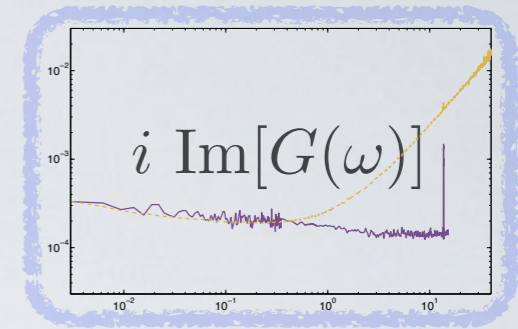
# Internal damping: viscoelasticity



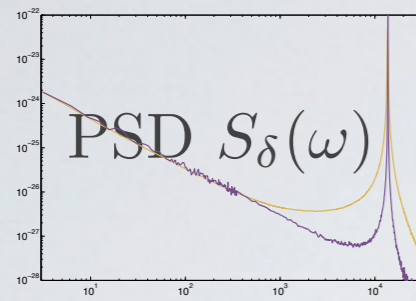
**FDT<sup>-1</sup> + KK**



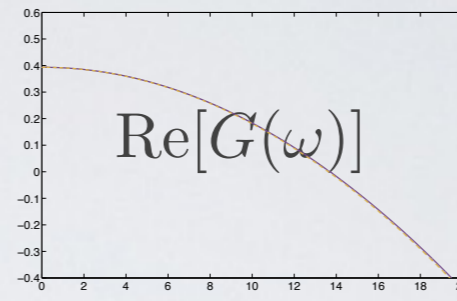
+



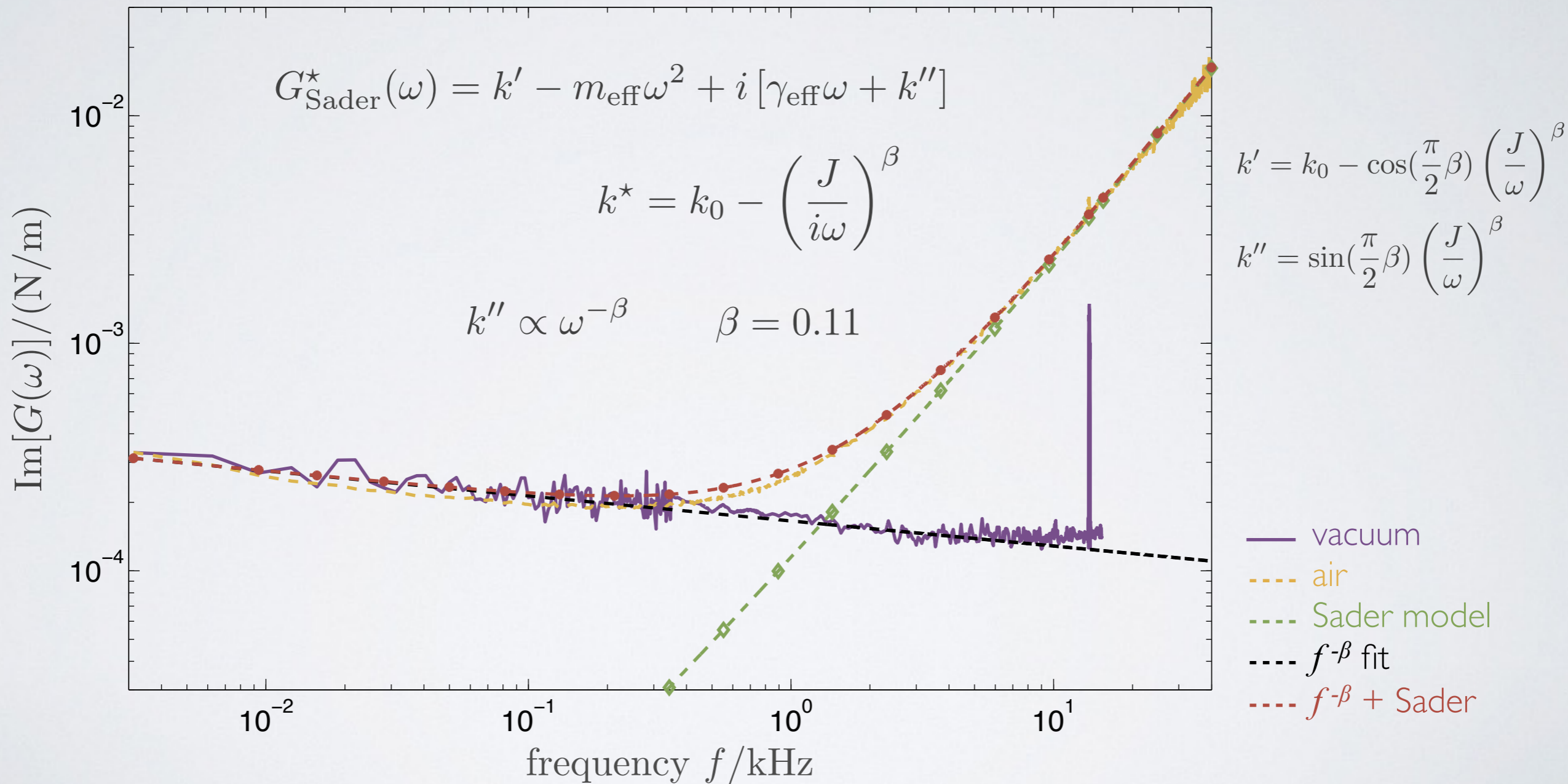
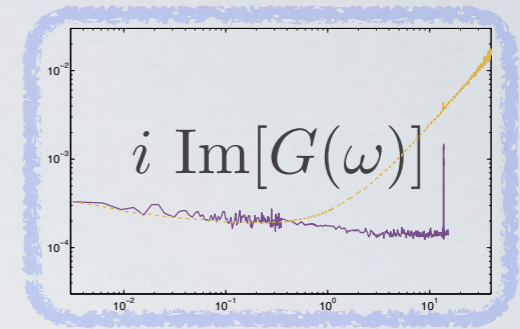
# Internal damping: viscoelasticity



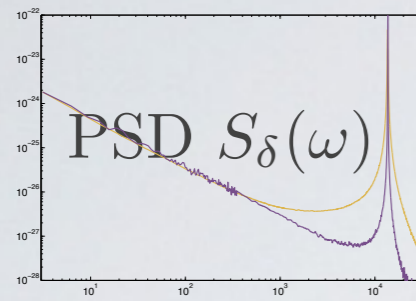
**FDT<sup>-1</sup> + KK**



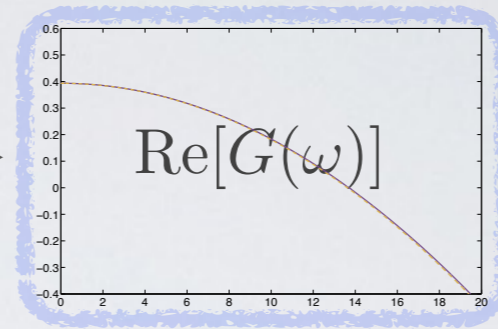
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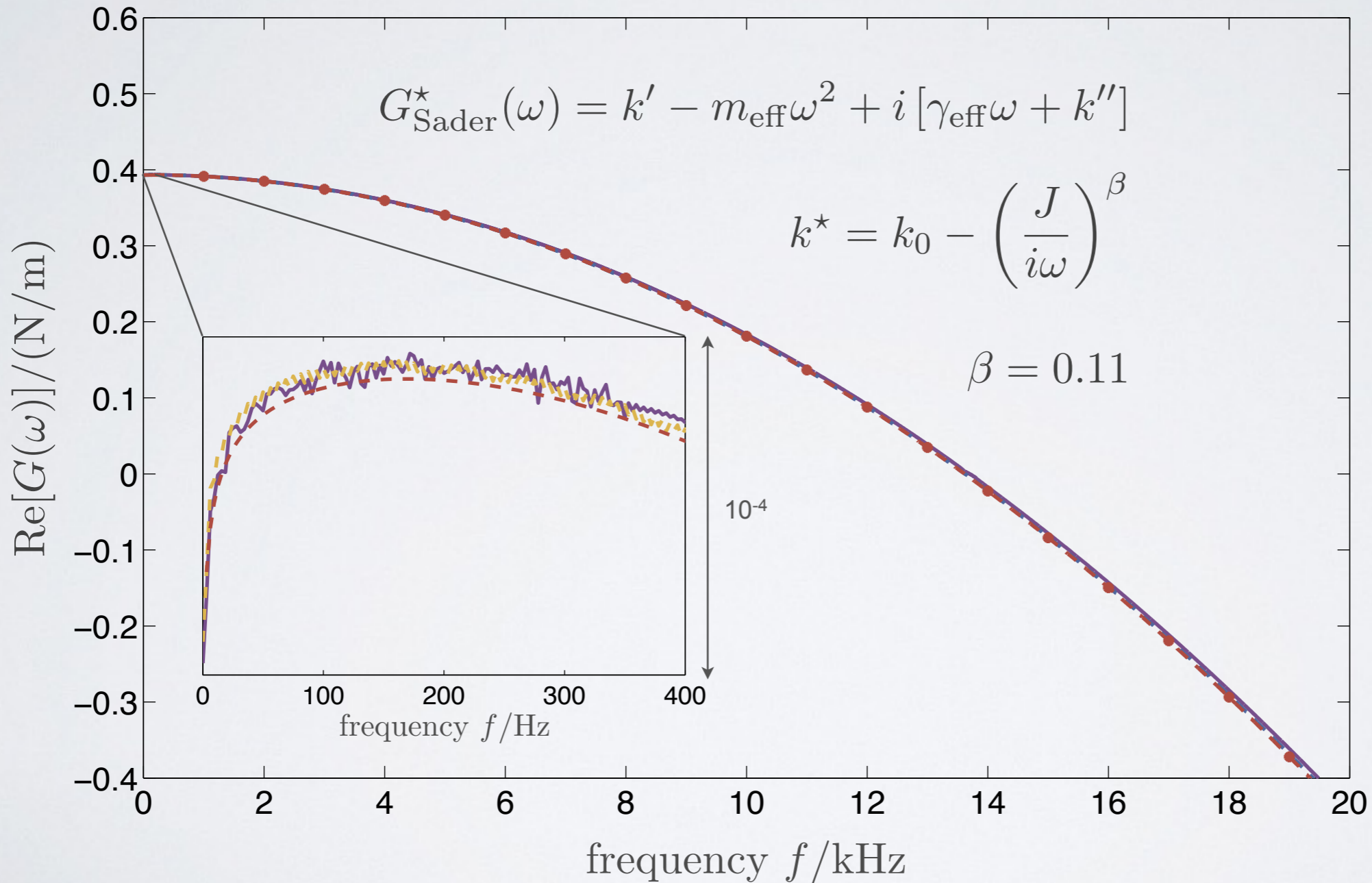
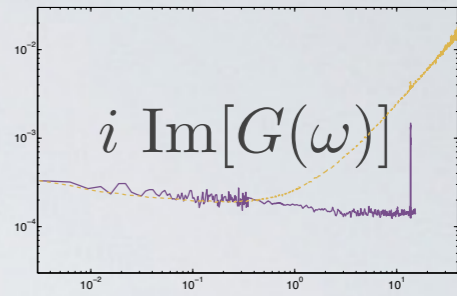
# Internal damping: viscoelasticity



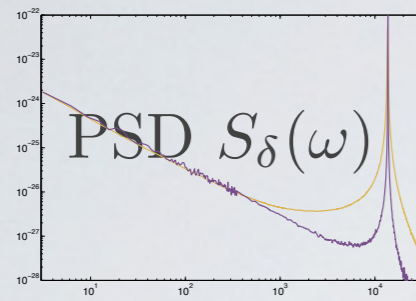
**FDT<sup>-1</sup> + KK**



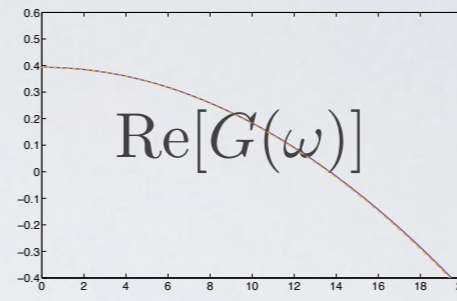
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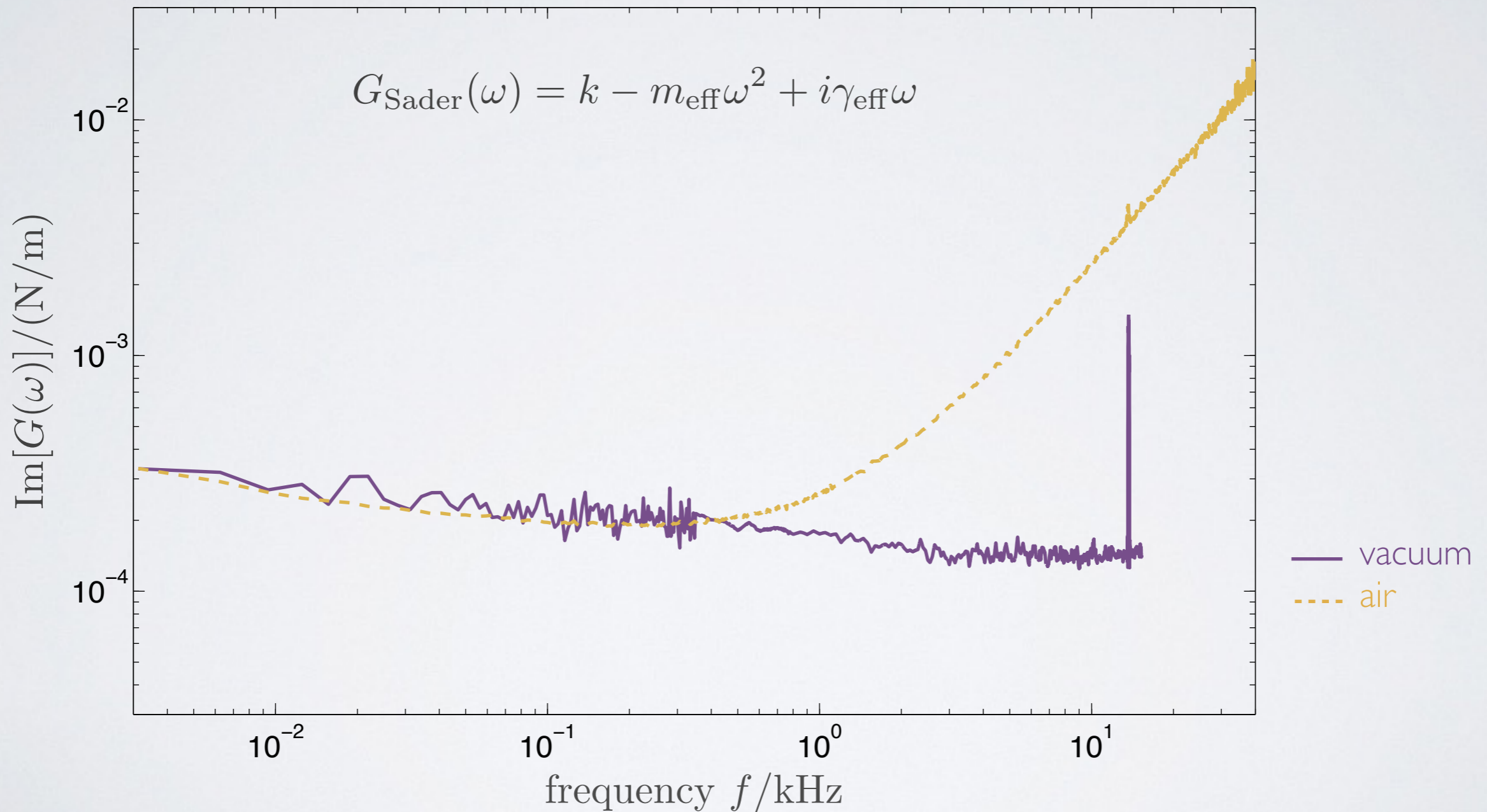
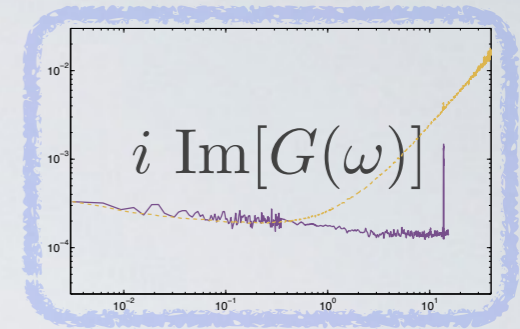
# Internal damping: viscoelasticity



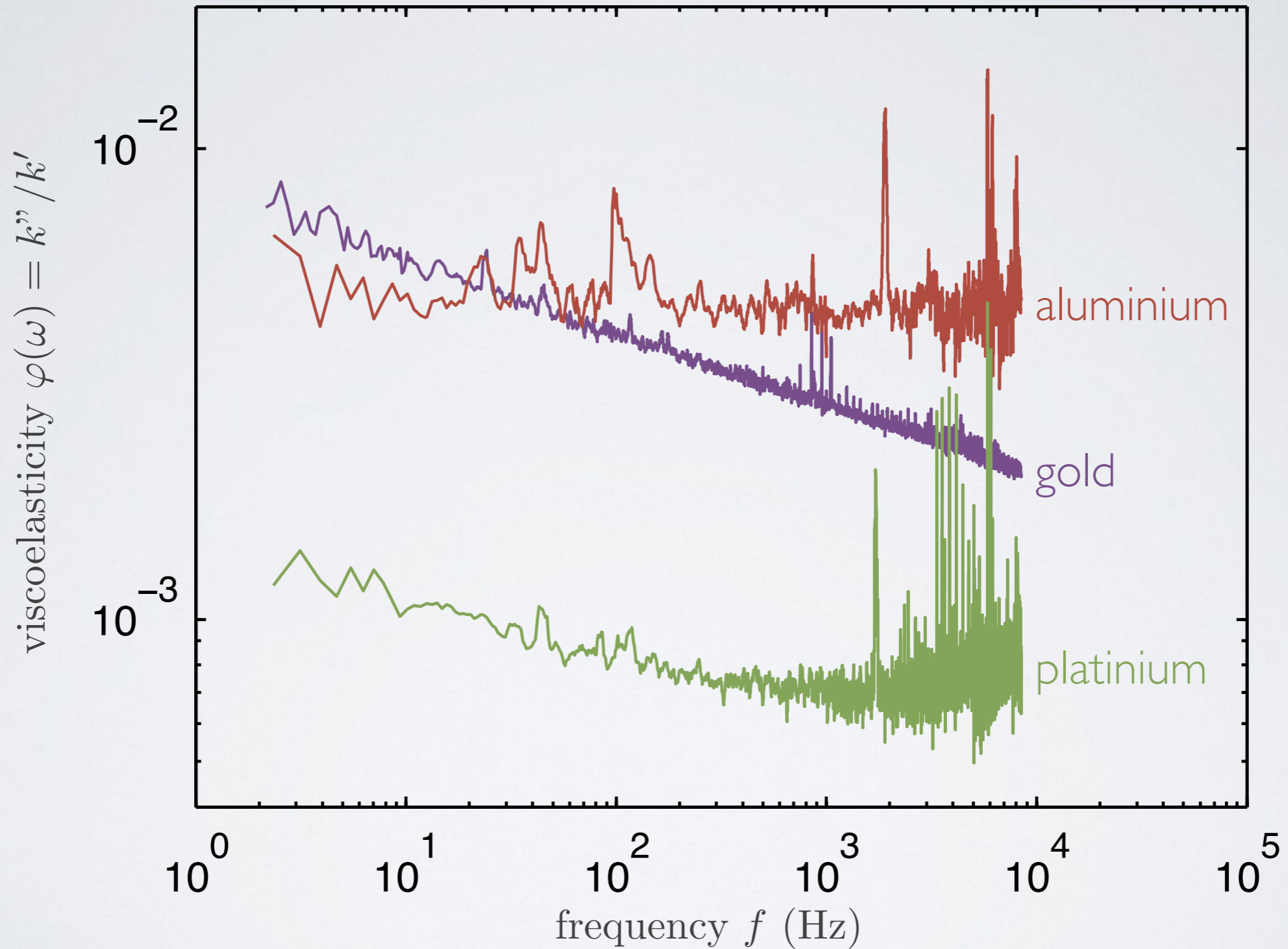
**FDT<sup>-1</sup> + KK**



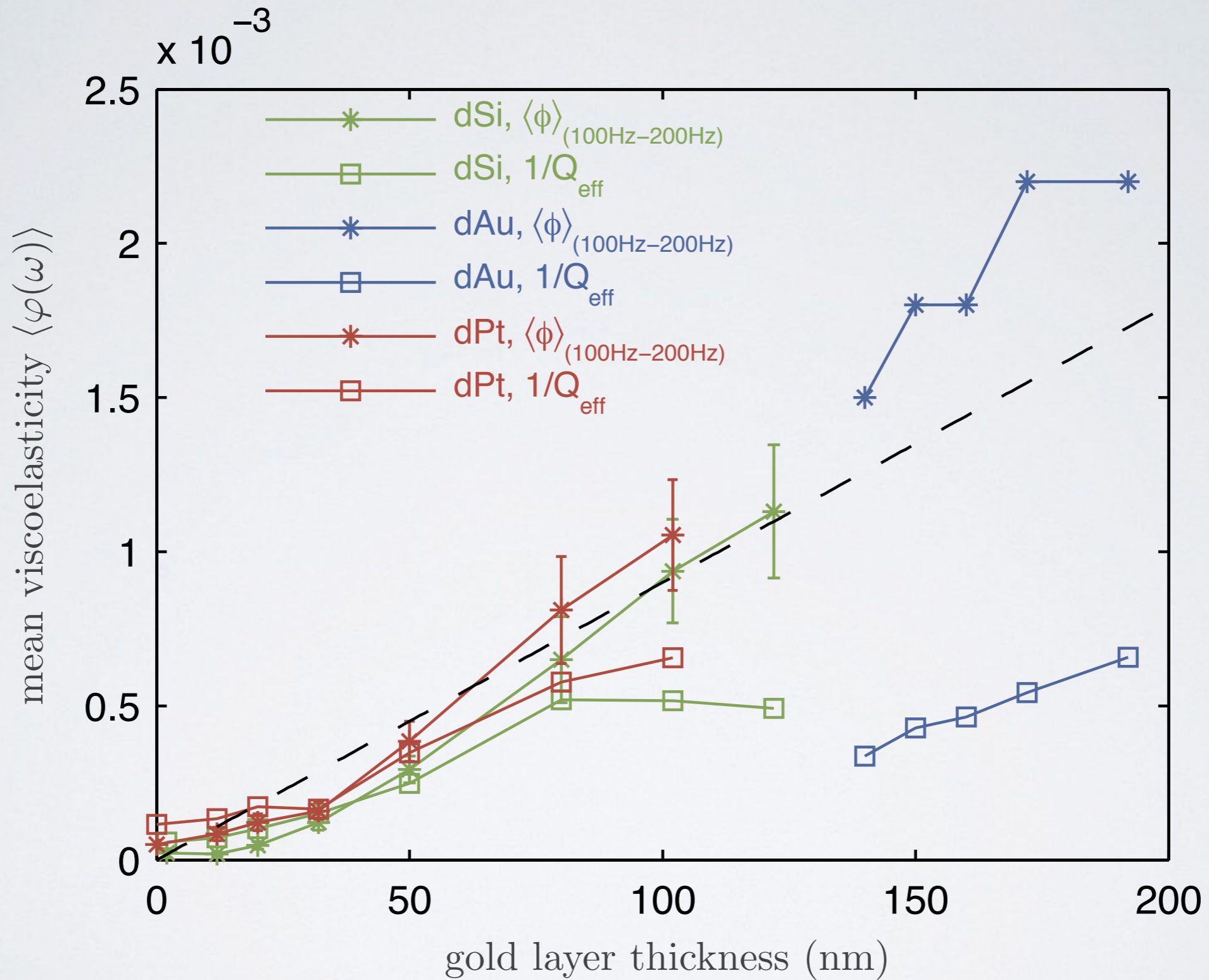
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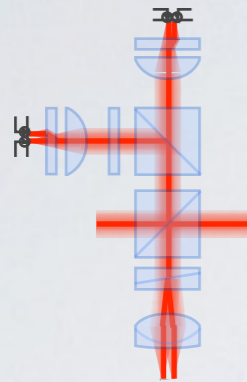


# Internal damping: viscoelasticity



# Internal damping: viscoelasticity

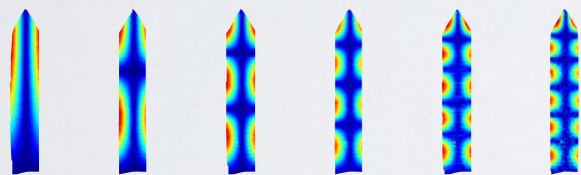




- Quadrature phase interferometry

Experimental setup

Measurement of thermal noise

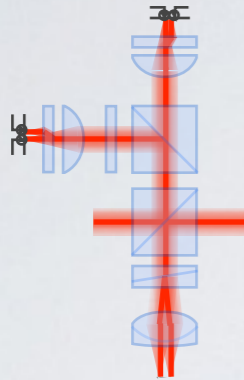


- Micro-cantilever response from thermal noise

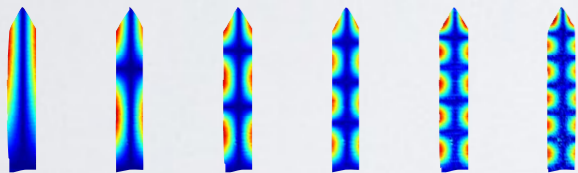
Full measurement of response with Kramers-Kronig relations

Viscoelasticity of coating layer



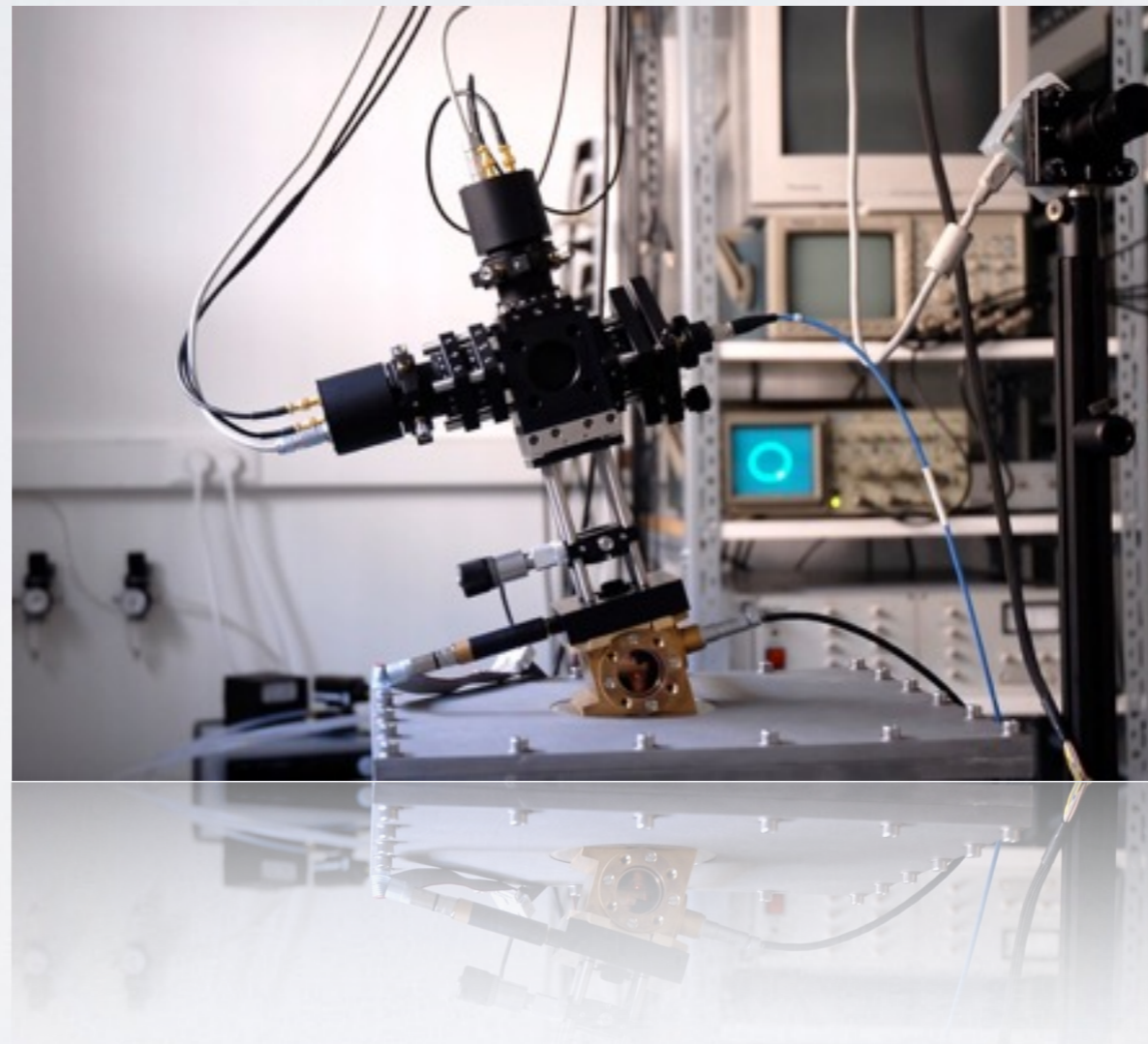


- Lowering the baseline noise
- Cryogenic operation
- Viscoelasticity of dielectric coatings
- Beyond FDT : fluctuations in out of equilibrium systems



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